




Università degli Studi dell'Insubria
Dipartimento di Scienze Teoriche e Applicate

How to Tell Apart the Good from the Bad: Setting Thresholds in Software Engineering

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(1) This material was developed jointly with Prof. Sandro Morasca



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The problem
Proposal 1: slope-based thresholds
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Final considerations


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The context

- Like in all engineering disciplines, Software Engineering practitioners need to manage the **quality** of software products and processes
 - ▶ monitor
 - ▶ control
 - ▶ evaluate
 - ▶ improve
 - ▶ ...
- In this presentation, we focus on the **faultiness** of software modules as the quality of interest


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A bit of terminology

- Faultiness
 - ▶ Presence of at least one fault in a module.
- Software module: a “piece” of software
 - ▶ A subsystem, a class, a procedure, etc.


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The context

- Quantitative information helps managing quality
- Measures
 - ▶ **Internal**, depending only on the software itself
 - Code measures: size, complexity, coupling, etc.
 - ▶ **External**, depending also on elements of the external world
 - Faultiness (depending on specifications)
 - Maintainability (depending on the required changes)
 - ...


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 Internal measures are not interesting by themselves

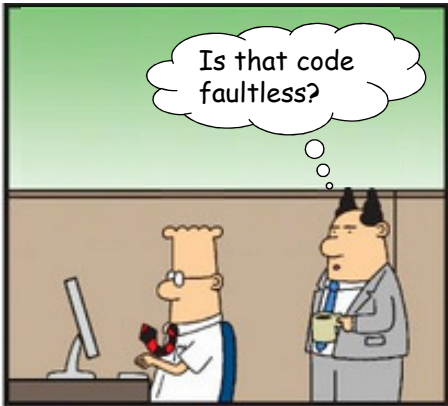
- The manager gets code measures, but he does not know how to interpret them.
- Note: even a *smart* manager who knows the meaning of RFC does not know what values of RFC are “good” and what values are “bad”.
 - This is typical of internal measures.




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 External measures are interesting

- The manager wants that only good quality code is released.
- Faultiness is what practitioners are really interested in for decision making along the software lifecycle
 - allocating V & V resources
 - controlling the production process
 - assessing the quality of the software under construction



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The context

- Unfortunately, **faultiness cannot be measured** based on the code only.
 - ▶ E.g., given a module, how can you “measure” if it is faulty or not?

- We need to **estimate** faultiness
 - ▶ We can use our knowledge about the module, i.e., the values of its internal measures

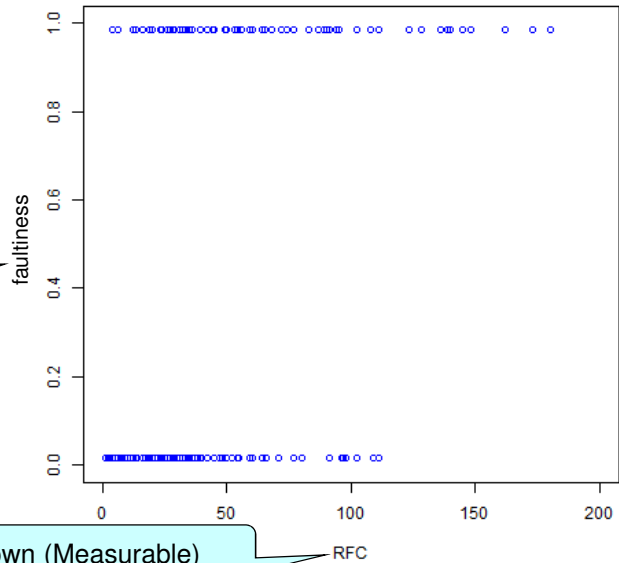
- But how?

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Hypothesis one: estimates are based uniquely on internal measures

- The test set
 - ▶ The data to be estimated
 - ▶ Every point in the plot is a module



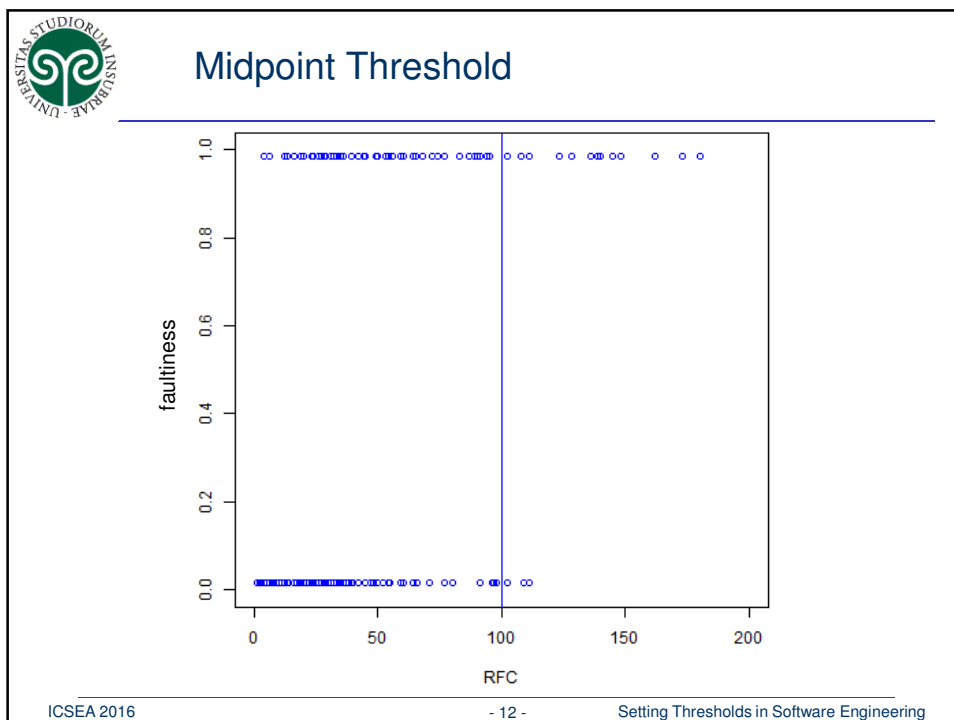
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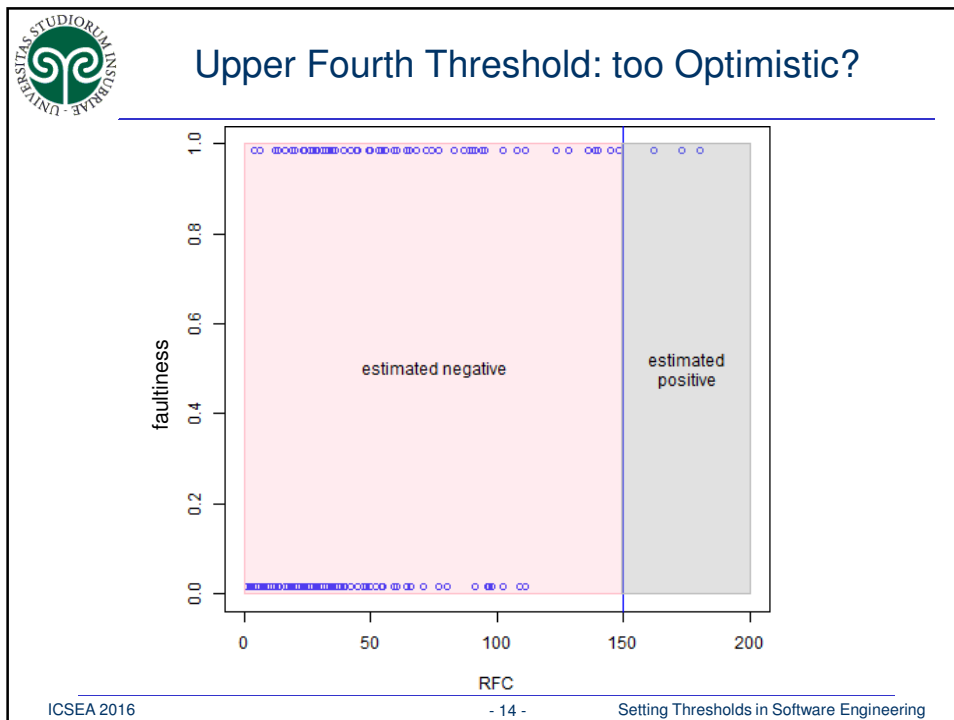
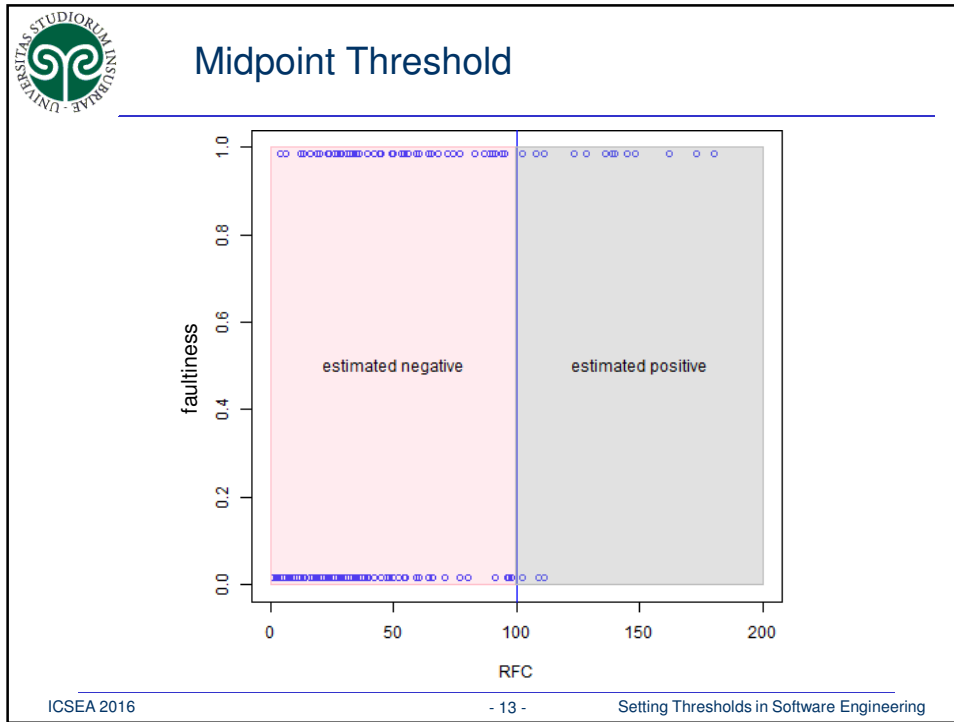


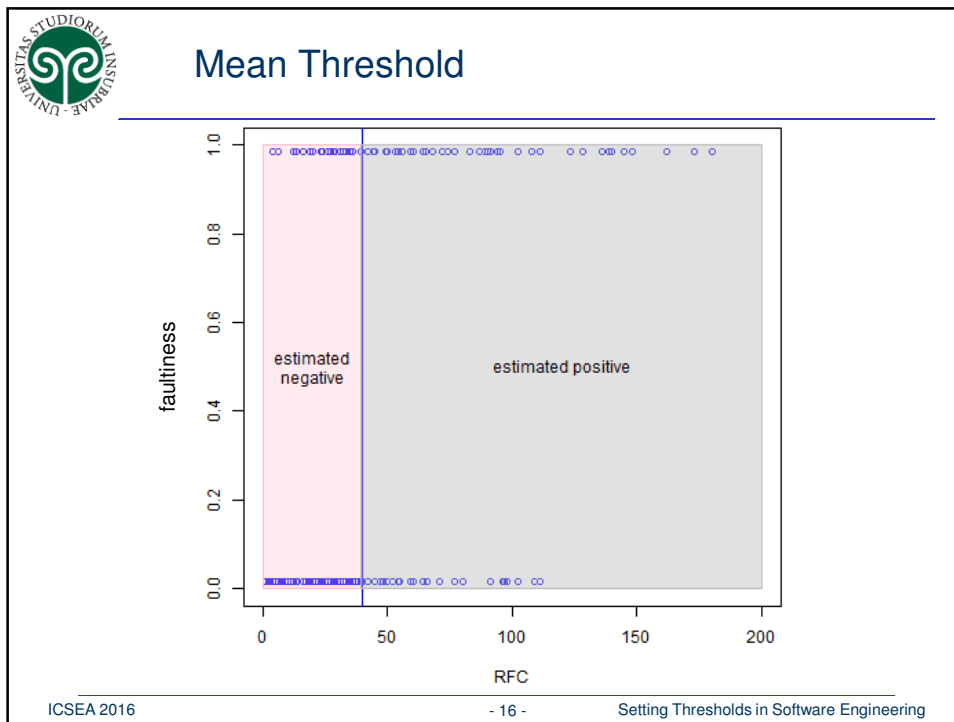
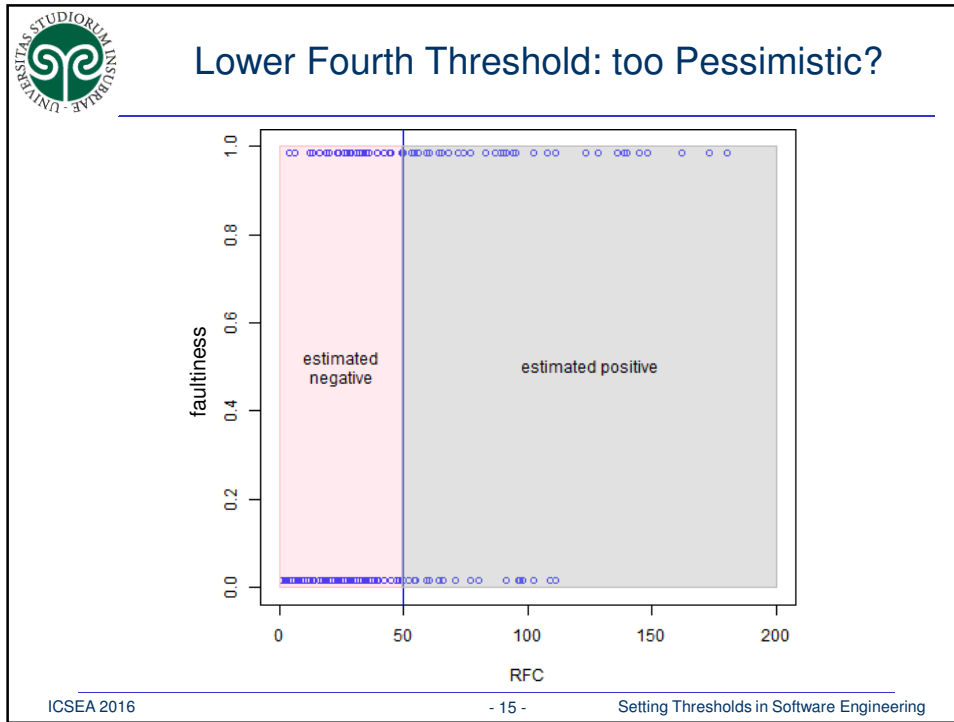
We need a threshold for estimating

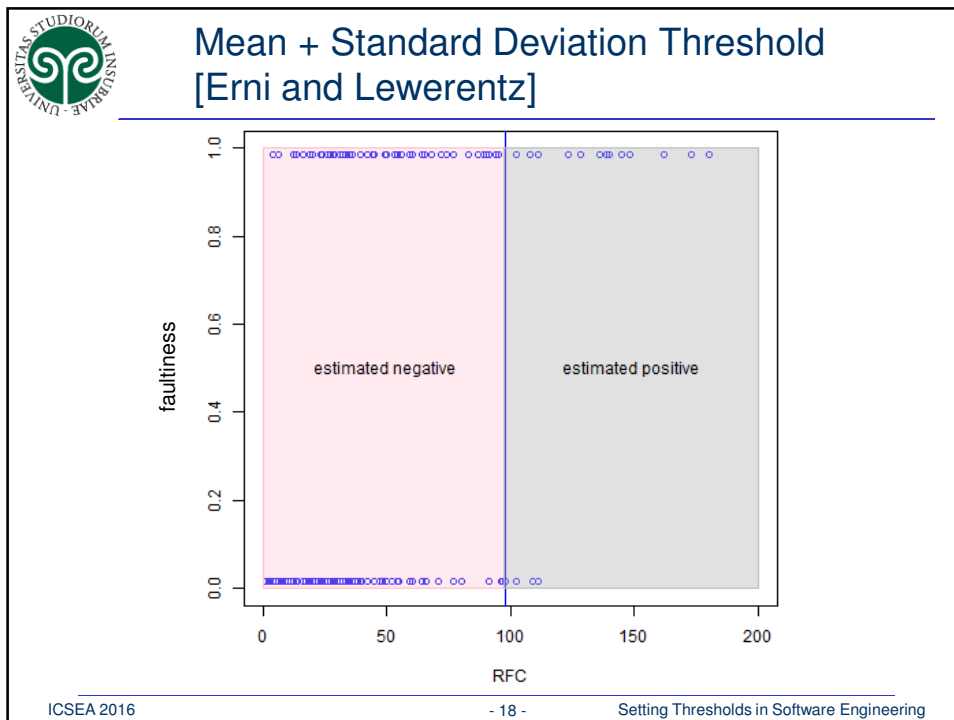
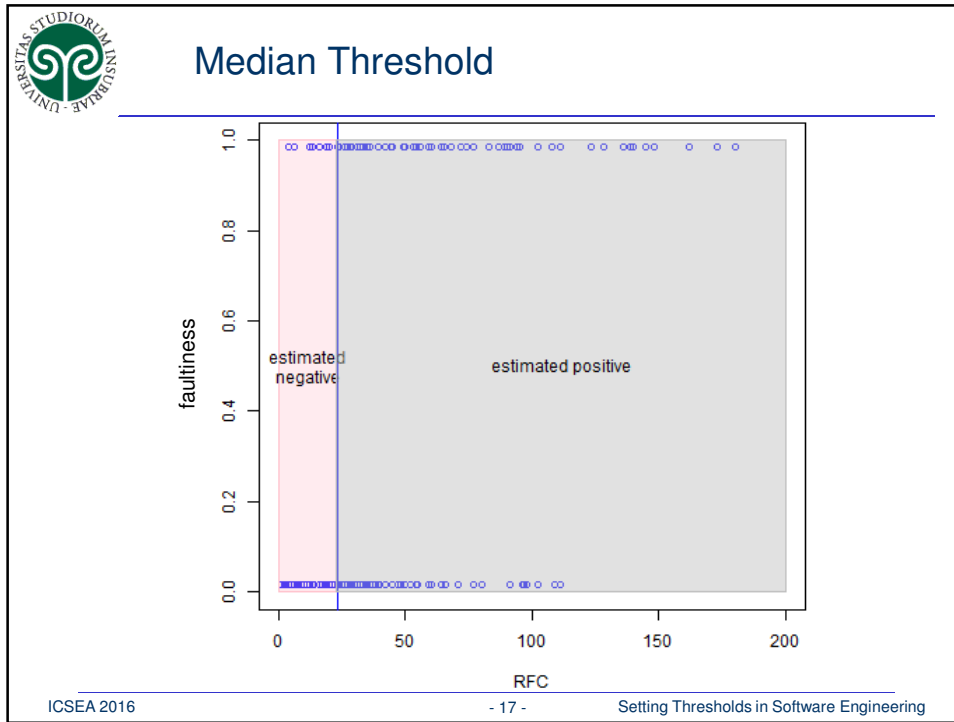
- Under the current hypothesis, estimates are based uniquely on internal measures
 - ▶ E.g., RFC, response for a class
- We need a threshold T such that
 - ▶ Modules whose RFC measure is greater than T are classified faulty
 - ▶ Modules whose RFC measure is not greater than T are classified not faulty
- Problem: how do we define threshold T ?
 - ▶ let's consider a few possibilities ...

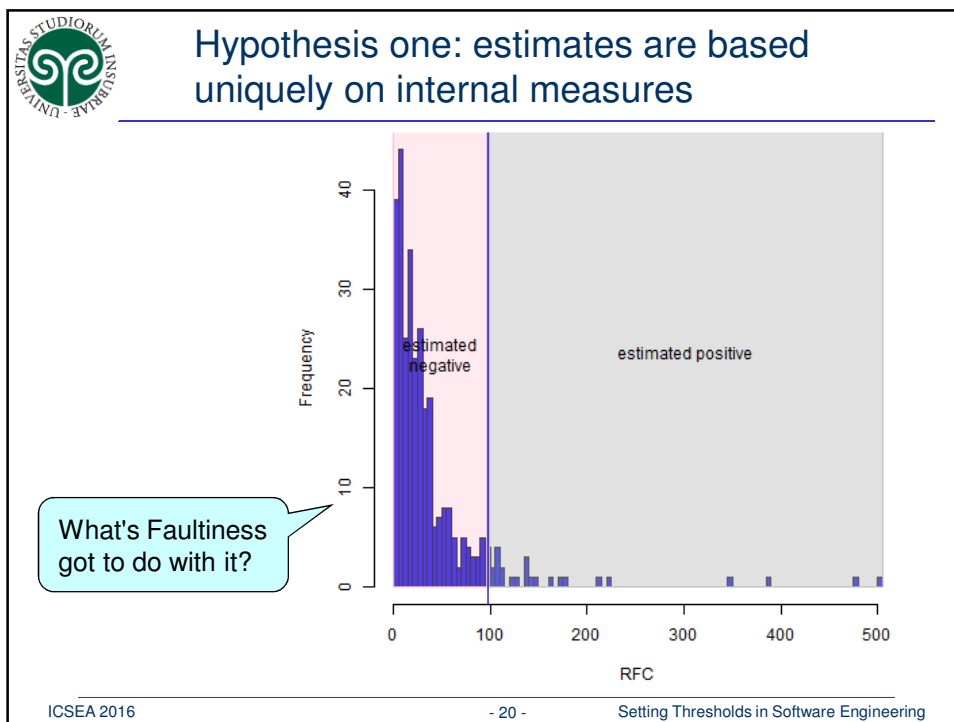
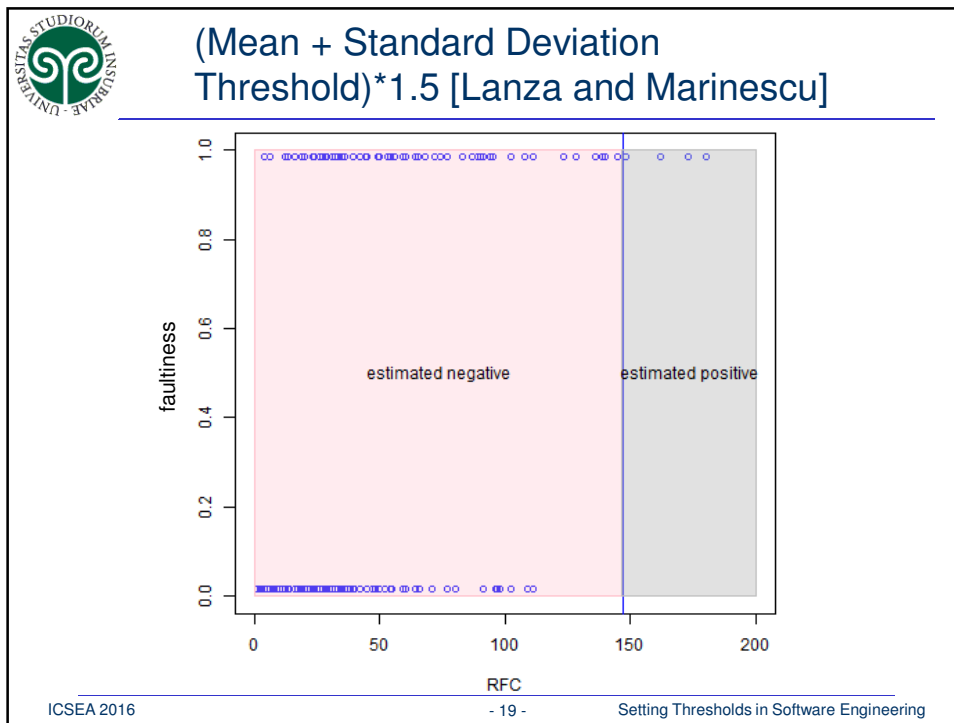
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Hypothesis one: estimates are based uniquely on internal measures

- Do we get good results (i.e., accurate estimates) with this strategy?
- Not really.
 - ▶ We shall see some experimental results at the end of the presentation.

Bad results could be expected.
If you try to estimate fault-proneness based on a measure that is known to be related to fault-proneness, but without taking into consideration how it is correlated to fault-proneness, your guess could easily be wrong!

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Hypothesis two: Use Internal Measures and Faultiness Data

- A faultiness estimation model can be built on top of
 - ▶ a fault-proneness estimation **model**
 - ▶ a fault-proneness **threshold**

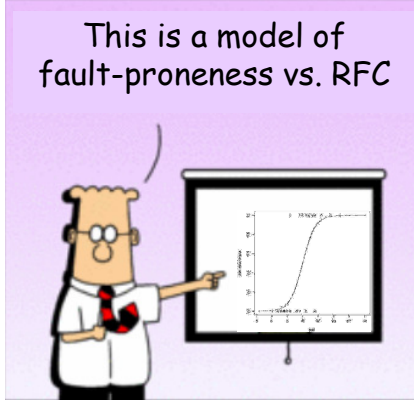
A common practice in many fields.
E.g., widely used in mechanical maintenance, or in medicine.

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Quality models available!

This is a model of
fault-proneness vs. RFC



- Models relating internal measures (CBO, WMC, RFC, etc.) to external quality (e.g., fault-proneness) are (often) available.
- These models “transform” internal measures with no practical meaning into meaningful indications.


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Models of fault-proneness

- Independent variable(s):
 - One or more internal measures
 - E.g., RFC, CBO, ...
- Dependent variable:
 - The quality of interest
 - In our case, fault-proneness
- Why fault-proneness instead of faultiness?
 - A model estimates the **probability of faultiness**, i.e., **fault-proneness**

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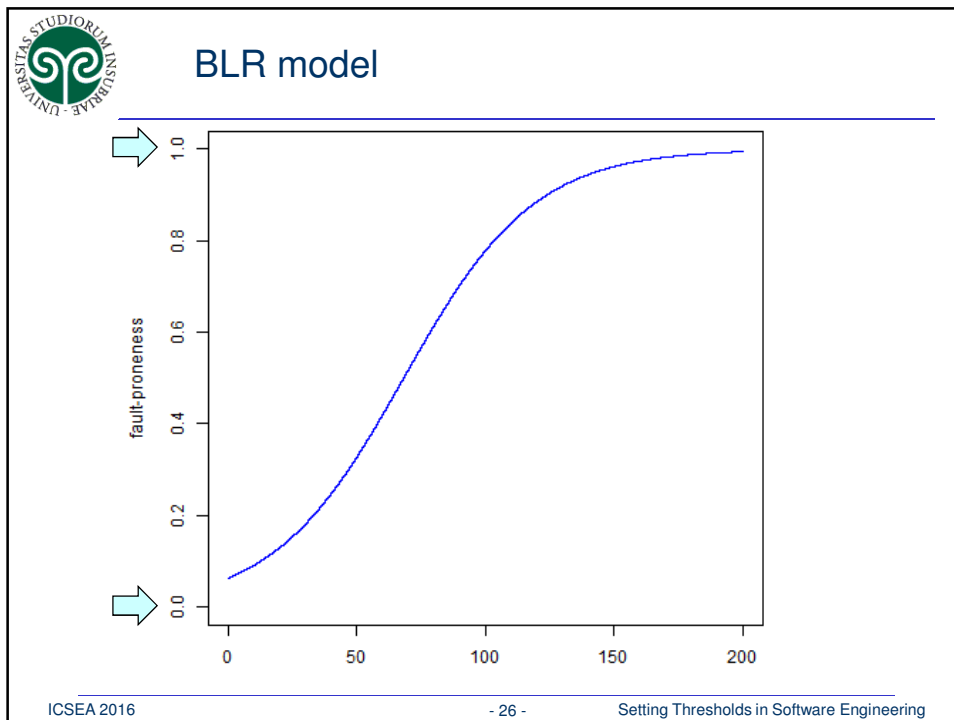


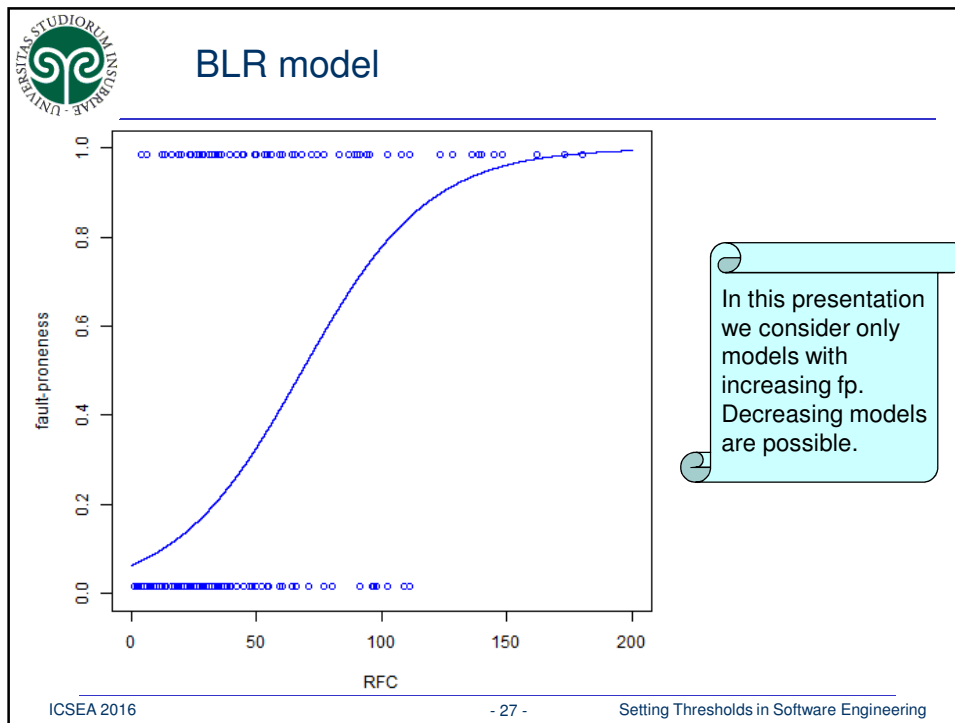
Binary Logistic Regression (BLR) models of fault-proneness

$$fp(x) = \frac{e^{logit(x)}}{1 + e^{logit(x)}}$$

- logit(X) is a linear function
 - ▶ univariate case: $c_0 + c_1X$
 - X is the internal measure
 - ▶ multivariate case: $c_0 + c_1X_1 + c_2X_2 + \dots$
 - $X_1, X_2 \dots$ are internal measures

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Other models

- Other types of models can be used, like, the Probit Binary Regression (PBR)

$$fp(z(\underline{X})) = \Phi(z(\underline{X})) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{z(\underline{X})} e^{-t^2/2} dt$$

- The resulting model is S-shaped, much like the BLR model.
- In this presentation we shall use only BLR models.
 - What we shall see here can be usually extended easily to other types of models.


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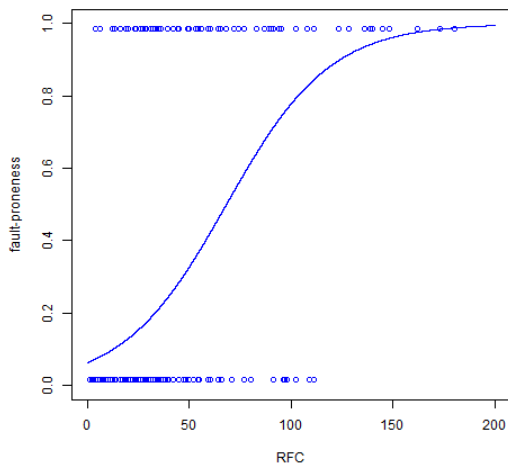
How to build models

- Assuming that we have proper data
 - ▶ E.g., a spreadsheet with
 - A row for each module
 - A column for each internal measure
 - A column for faultiness
- We need a statistical tool to compute the model.
- I suggest R
 - ▶ Open-source and free
 - ▶ Supported by a huge community
 - ▶ There are books and documentation available
 - ▶ Provides a wealth of statistical tools
 - To make sure that the models found are statistically significant
 - To test their “goodness”
 - Hosmer test, likelihood ratio test, ...


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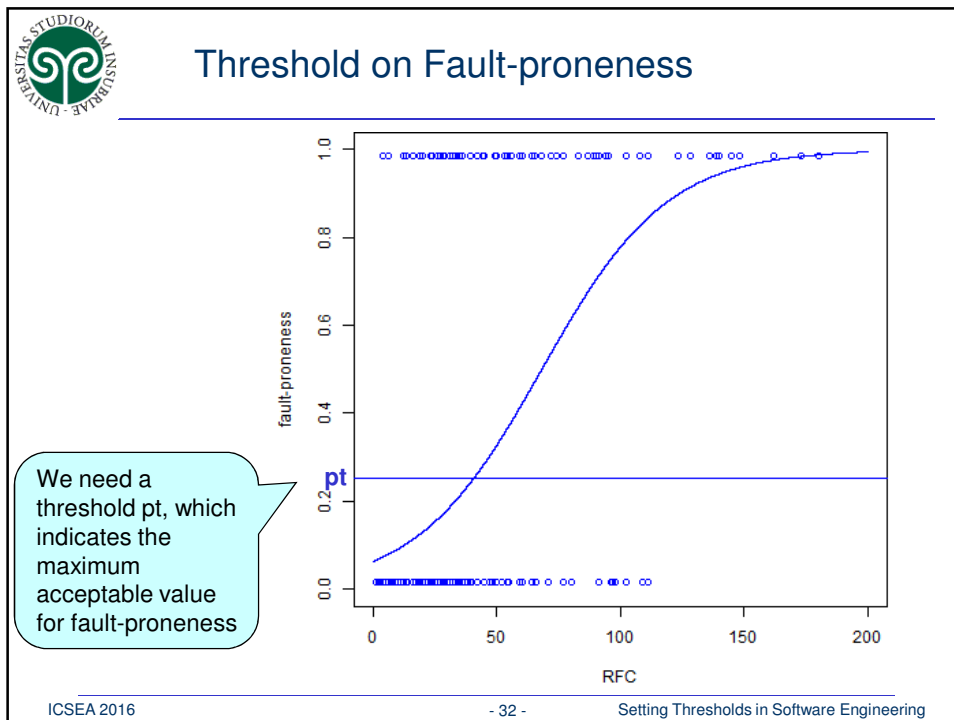
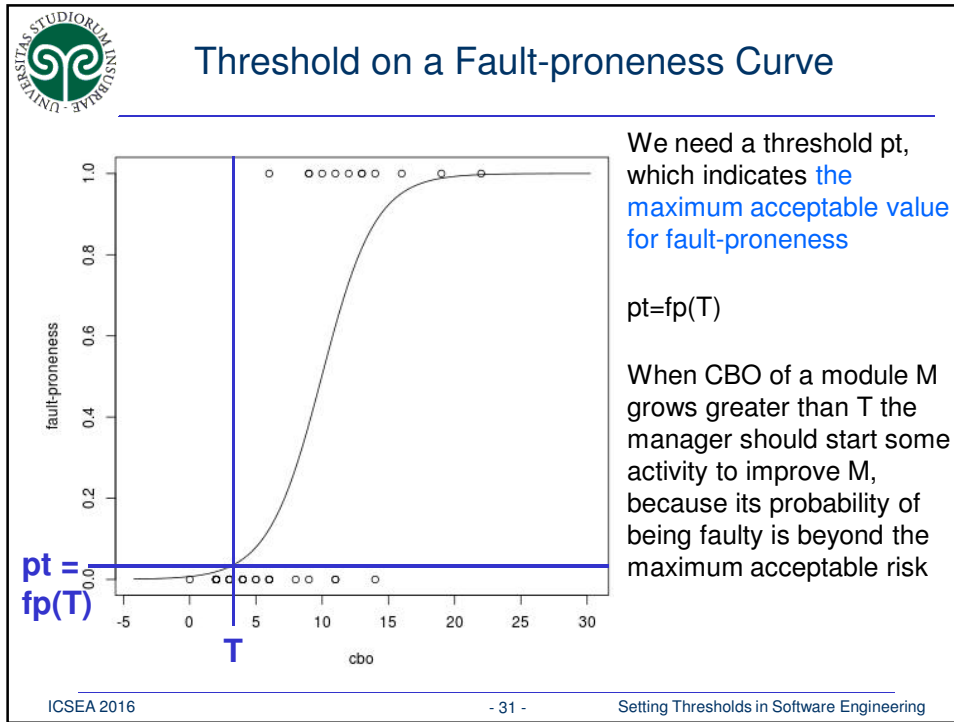
How to use a model?

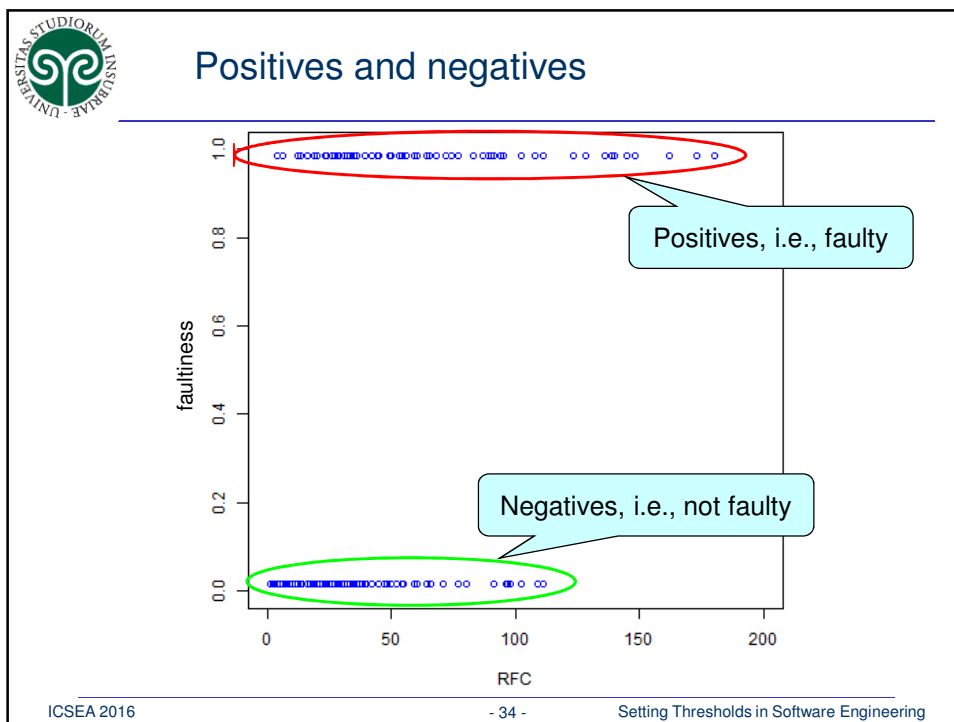
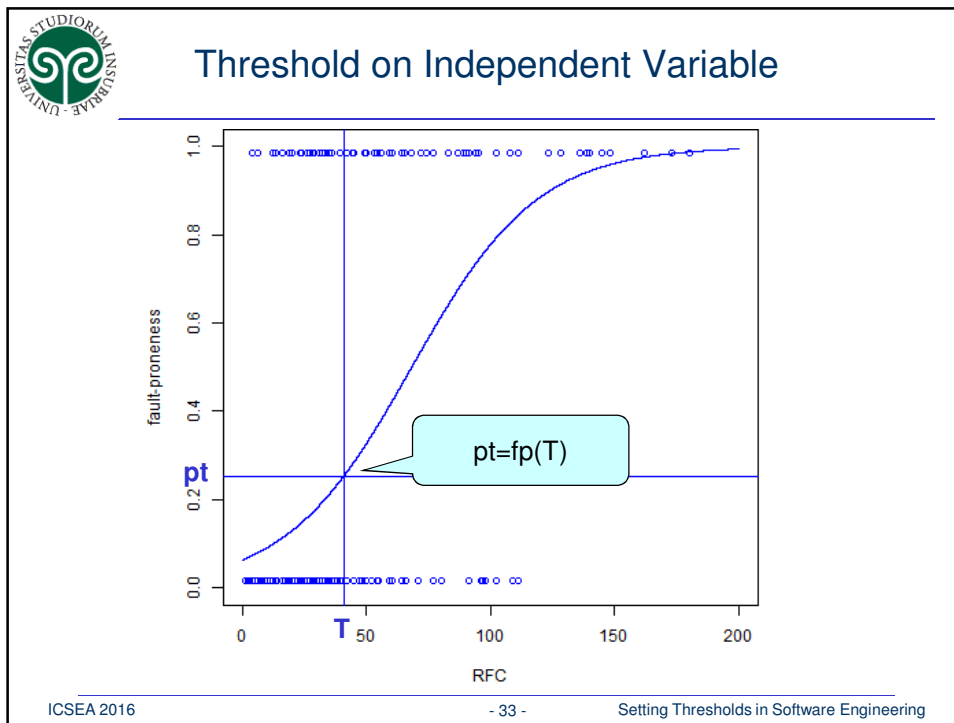


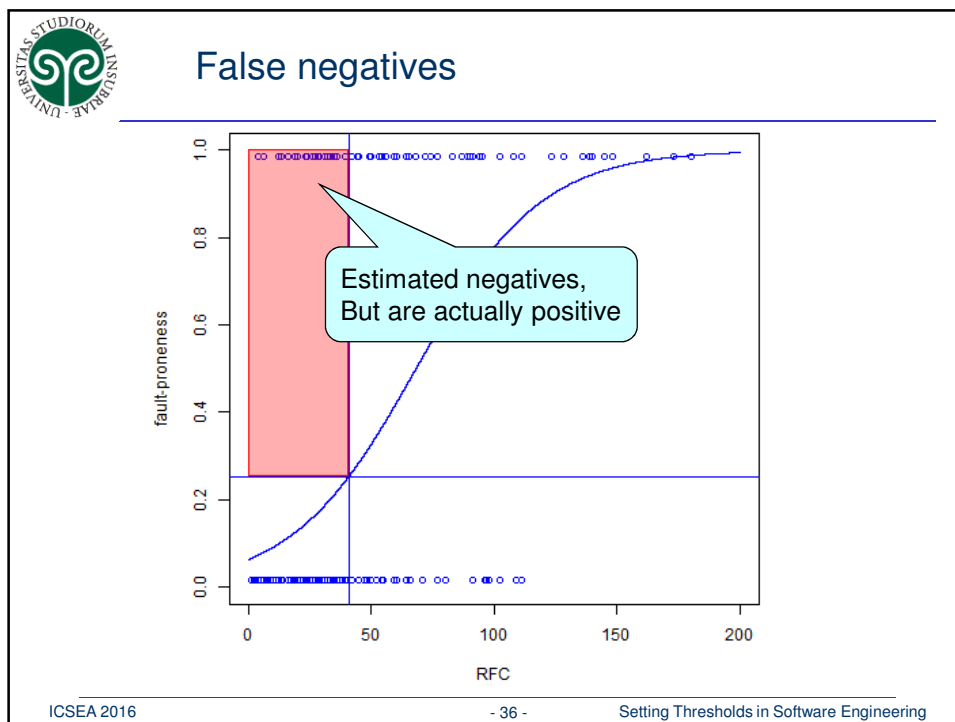
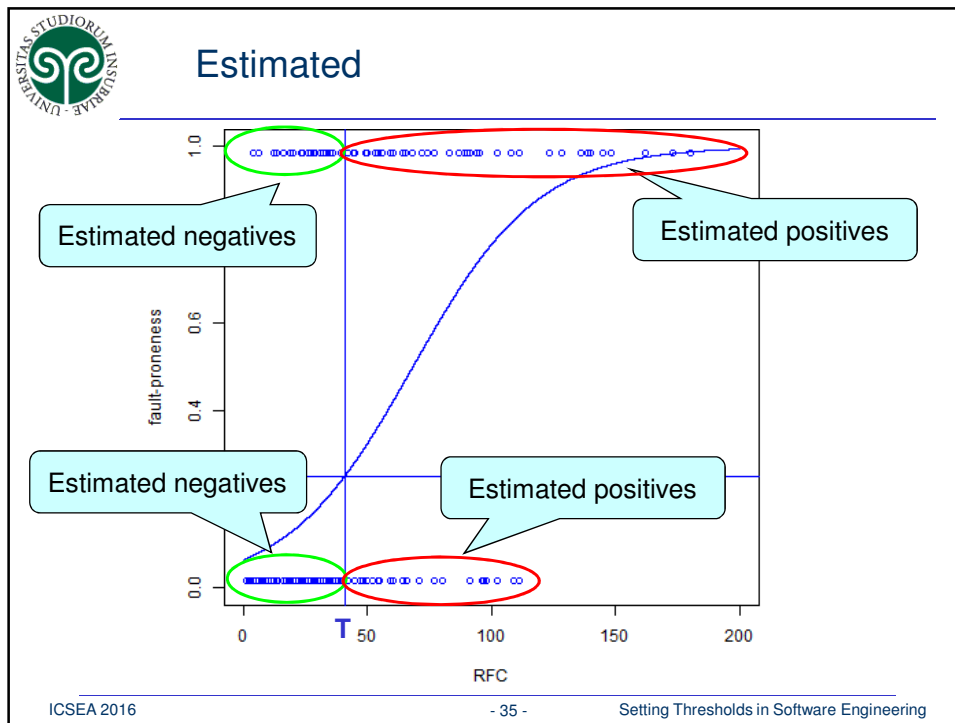
- How do we use the knowledge that an internal measure is related to the probability of faultiness?

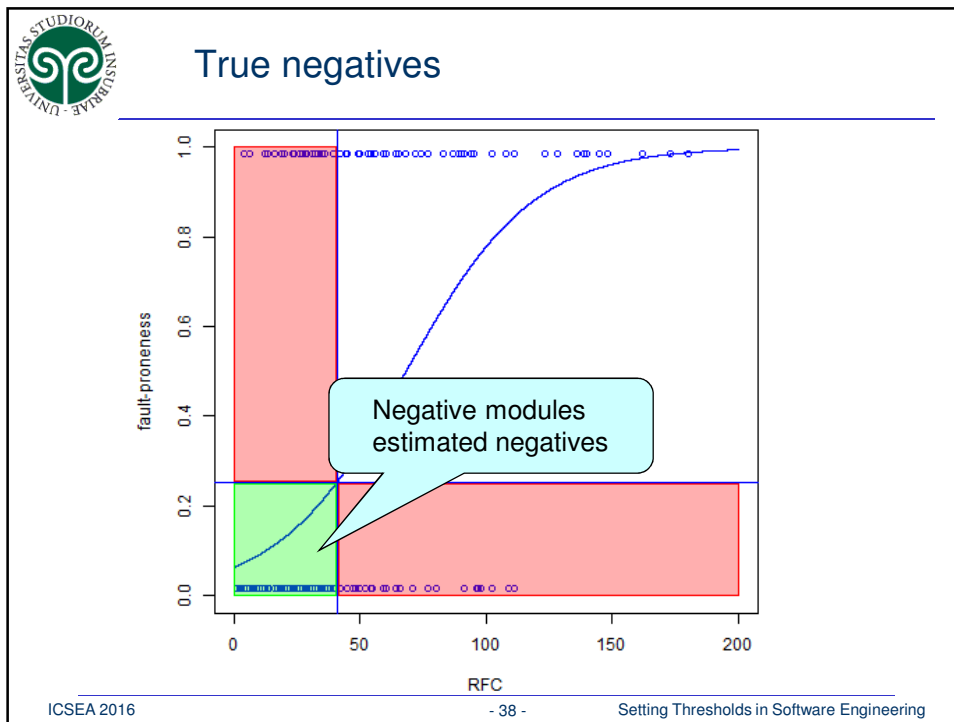
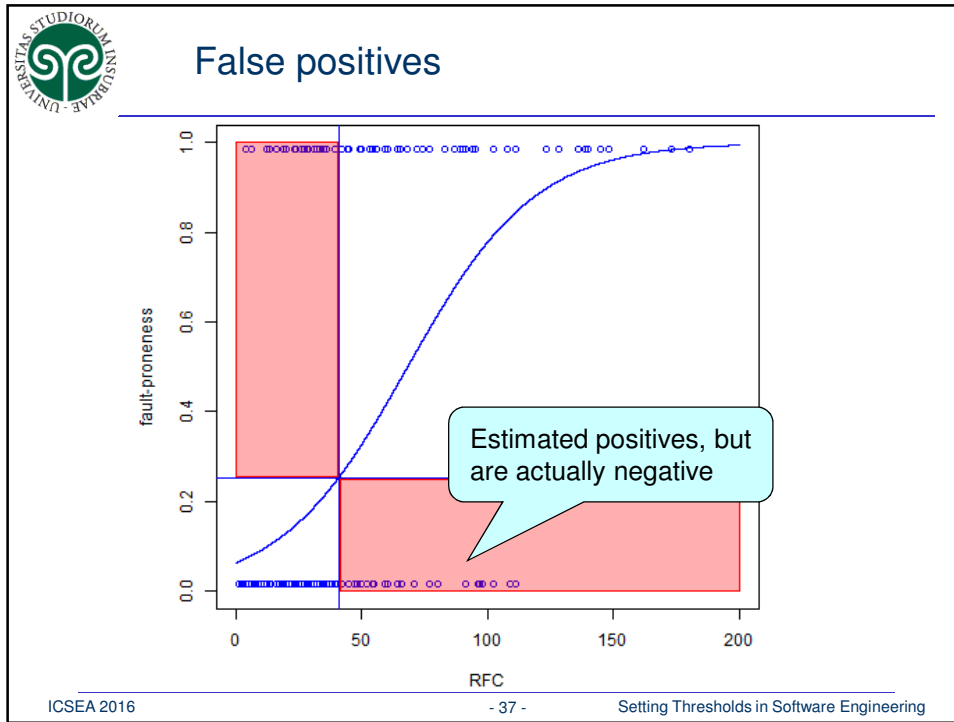


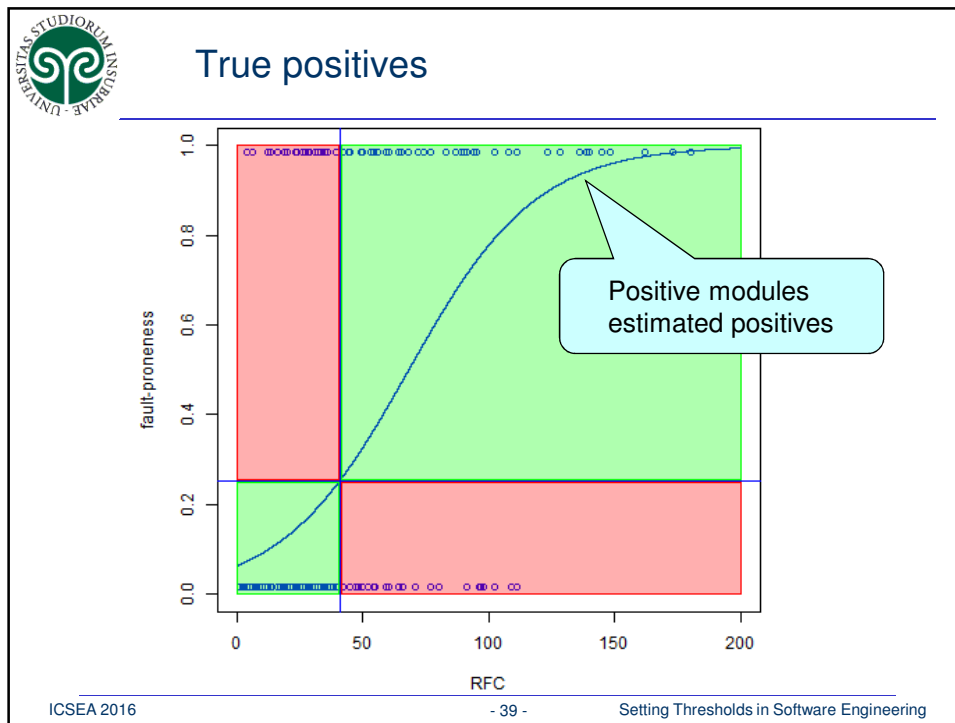
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How good is a model?

- We need to evaluate how good is a model, i.e., how accurate are its estimates.
- Informally, we want
 - ▶ Many true positives and true negatives
 - ▶ As few as possible false negatives and false positives.

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Estimated/Actual Faultiness Contingency Tables

- We need to check how close estimated faultiness is to actual faultiness

		Actual		
		Non-faulty	Faulty	Total
Estimated	Non-faulty	TN	FN	EN
	Faulty	FP	TP	EP
	Total	AN	AP	n

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Accuracy indicators


- Precision: proportion of estimated positives that are actually positive

$$Precision = \frac{TP}{EP}$$
- Recall: proportion of actual positives that are estimated positives

$$Recall = \frac{TP}{AP}$$
- F-measure: harmonic mean of Precision and Recall

$$Fmeasure = \frac{2}{\frac{1}{Recall} + \frac{1}{Precision}}$$


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The real problem

- How should we choose pt (hence, T)?


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Some possible thresholds

- $fp = 0.5$ (Fifty)
 - ▶ a theoretical threshold, used for no prior knowledge, same value no matter the application or discipline
- $fp = \frac{AP}{n}$ (All)
 - ▶ This is the proportion of faulty modules in the entire data set
 - Useful to evaluate the accuracy of the proposed thresholds
 - It is the value you get with a constant logit


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Why not using Fifty or All thresholds?

- Fifty does not use any knowledge about the actual modules.
 - ▶ If AP/n is 0.1 and you use 0.5 thresholds, you are going to have a lot of false positives
 - ▶ If AP/n is 0.9 and you use 0.5 thresholds, you are going to have a lot of false negatives
- AP/n could be a reasonable choice. Unfortunately, AP is not known at estimation time.


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Slope-based Thresholds¹

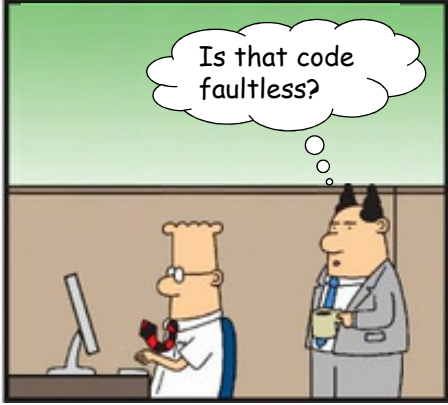
- A first proposal is applicable when we want to identify “**early symptoms**” of possible faultiness

¹ Sandro Morasca and Luigi Lavazza, “Slope-based Fault-proneness Thresholds for Software Engineering Measures”, *EASE 2016*


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 **The problem**

- The manager wants that only good quality code is released.
- He wants to get some evidence that lets him take action **as soon as** the quality of a module under development becomes **“not good enough”**.



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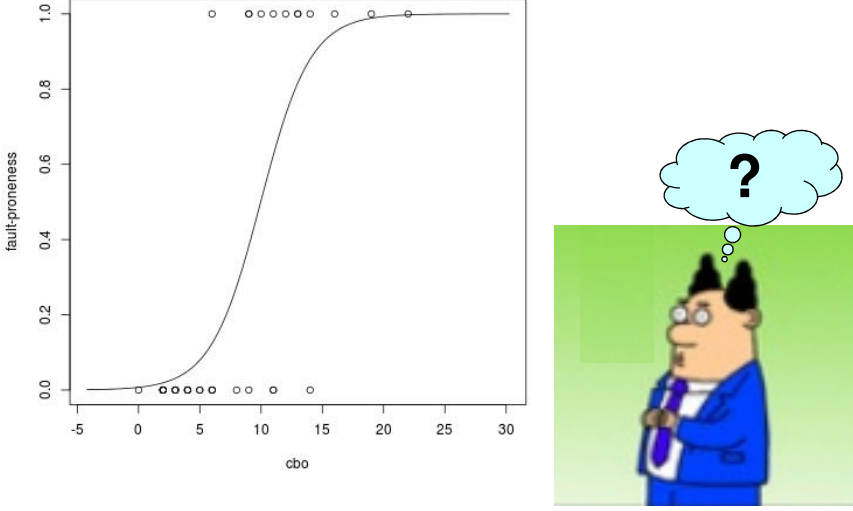
 **We have a model**

- The model is built as shown before, based on data from previous developments (e.g., of previous releases).

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Yes, but ... how to use the model?

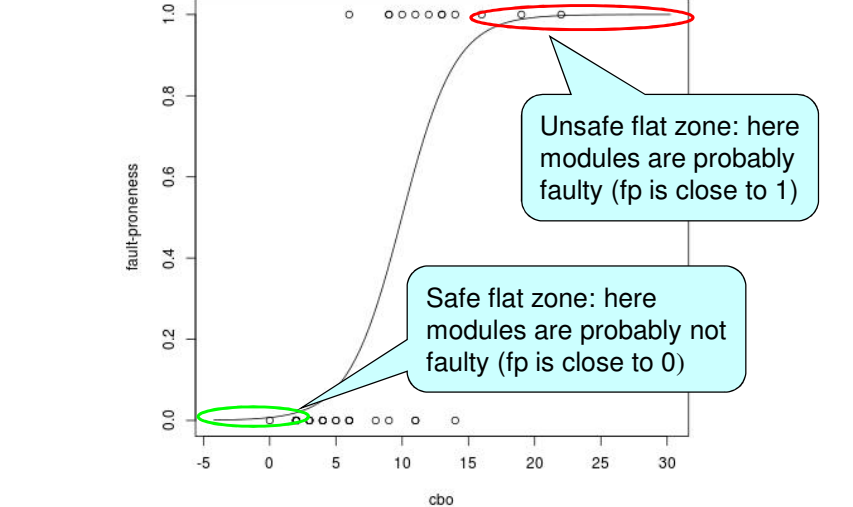


The graph shows a sigmoid curve representing fault-proneness as a function of cbo. The y-axis is labeled 'fault-proneness' and ranges from 0.0 to 1.0. The x-axis is labeled 'cbo' and ranges from -5 to 30. Data points are plotted as small circles, showing a transition from 0.0 to 1.0 between cbo values of approximately 5 and 20. To the right of the graph is a cartoon character in a blue suit with a thought bubble containing a question mark above his head.

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What does the model tell us?




The graph is identical to the one in slide 51. It features a sigmoid curve of fault-proneness vs cbo. Two callout boxes are present: one at the top right pointing to the flat zone where fault-proneness is near 1.0, and one at the bottom left pointing to the flat zone where fault-proneness is near 0.0. The top callout is circled in red, and the bottom callout is circled in green.

Unsafe flat zone: here modules are probably faulty (fp is close to 1)

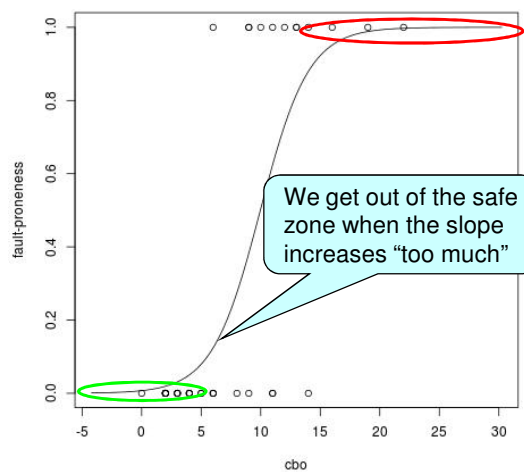
Safe flat zone: here modules are probably not faulty (fp is close to 0)

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Slope-based thresholds

- When a module is created its CBO is zero.
- Then, while the module is being implemented, CBO increases over time
- We want to identify “early symptoms” of possible faultiness
- Idea: we need to constrain CBO to be less than a value CBO_{MAX} where small variations of CBO imply large variations of $fp(CBO)$

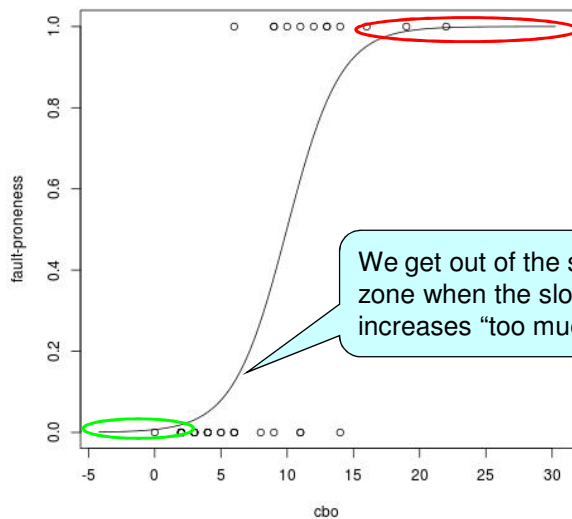


We get out of the safe zone when the slope increases “too much”

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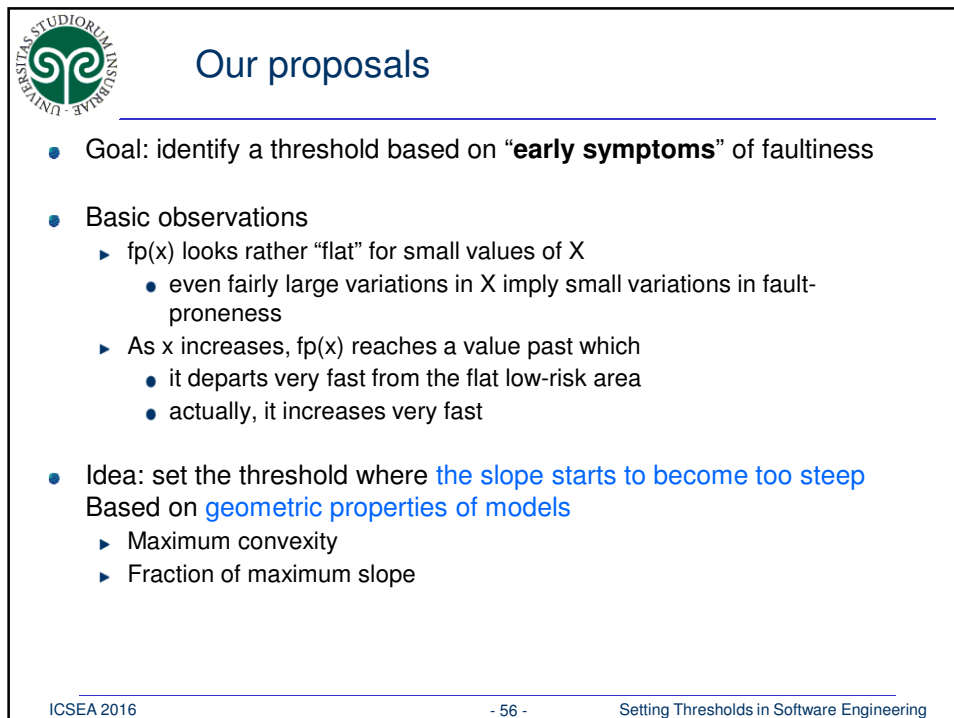
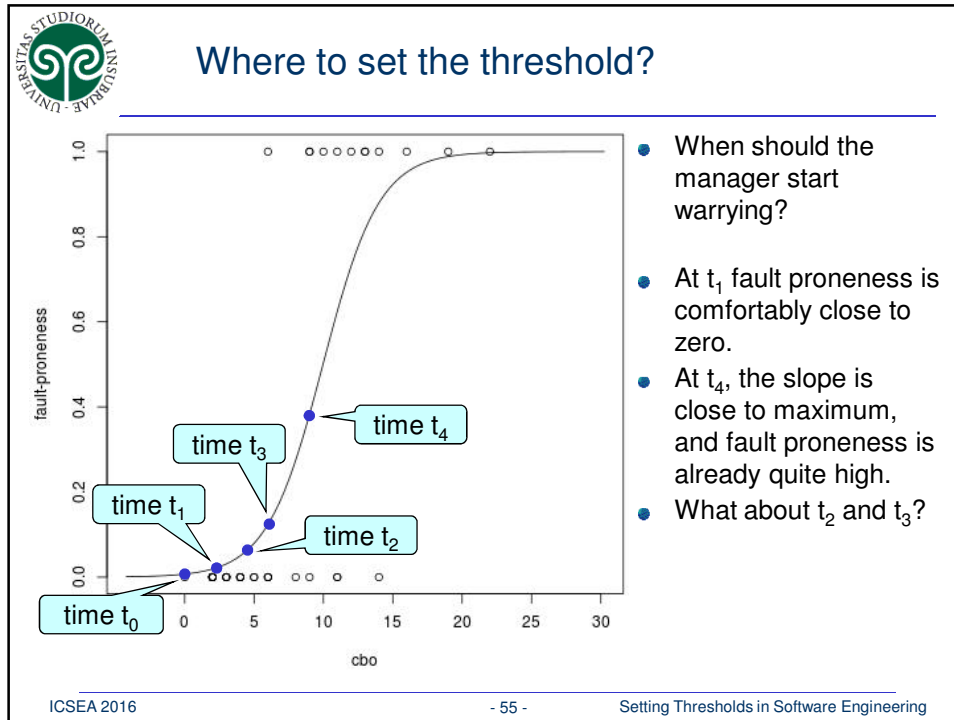



The basic idea



We get out of the safe zone when the slope increases “too much”

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Proposal 1: Maximum Convexity (MC)

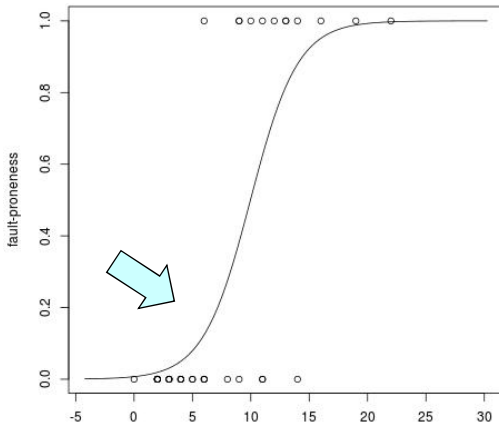
- At the beginning the slope/direction of $fp(X)$ changes very slowly
- At the end the slope/direction of $fp(X)$ changes very slowly too
- But, in between the slope/direction of $fp(X)$ changes much faster
- We define the threshold as the value x_{MC} of X in which $fp(X)$ changes slope/direction the fastest

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Maximum convexity (MC)

- Slope is measured by $fp'(X)$
- Slope change is measured by $fp''(X)$, i.e., convexity
- Since we are looking for the point where $fp''(X)$ is maximum, x_{MC} is such that $fp'''(x_{MC}) = 0$
- Beware x_{MC} is not necessarily where $fp(X)$ is steepest or even "too steep"



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Proposal 2: Fraction of Maximum Slope

- It might be too late to wait until the curve has reached maximum slope fp'_{max}
- Define the threshold as the point x_{rMS} such that $fp'(x_{rMS})$ is a fraction r of fp'_{max}

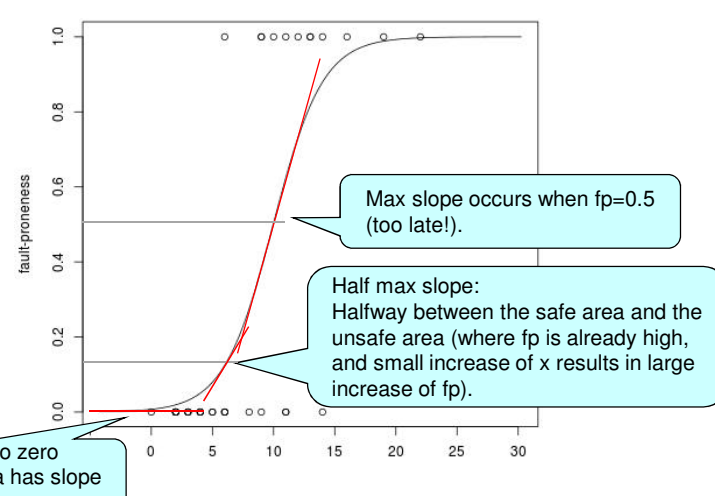
$$fp'(x_{rMS}) = r fp'_{max}$$

- The value of r is set by the practitioners, based on their goals
- Via empirical studies, we found that $r = 0.5$ is a reasonable choice.
 - ▶ Hence, we look for $x_{MS/2}$, where the slope is half the maximum value.

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Half maximum slope (MS/2)




Min slope tends to zero
 The safe flat area has slope close to zero

Max slope occurs when $fp=0.5$
 (too late!).

Half max slope:
 Halfway between the safe area and the unsafe area (where fp is already high, and small increase of x results in large increase of fp).

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MC threshold values

$$x_{MC} = \frac{1}{c_1} (\ln(2 - \sqrt{3}) - c_0) \approx -\frac{1.55 + c_0}{c_1}$$

$$fp(x_{MC}) = \frac{1}{2} - \frac{\sqrt{3}}{6} \approx 0.2113$$

The maximum convexity is always positioned where $fp=0.2113$

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MS/2 threshold values

$$x_{rMS} = \frac{1}{c_1} \left(\ln \left(\frac{1 - \sqrt{1-r}}{1 + \sqrt{1-r}} \right) - c_0 \right)$$

$$fp(x_{rMS}) = \frac{1}{2} - \frac{\sqrt{1-r}}{2}$$

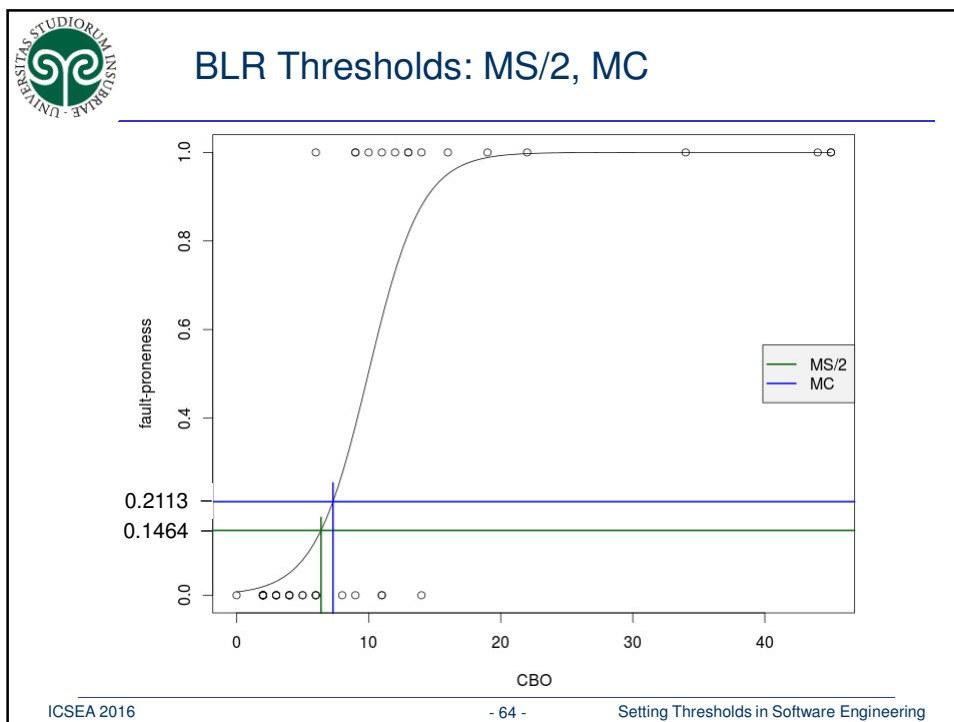
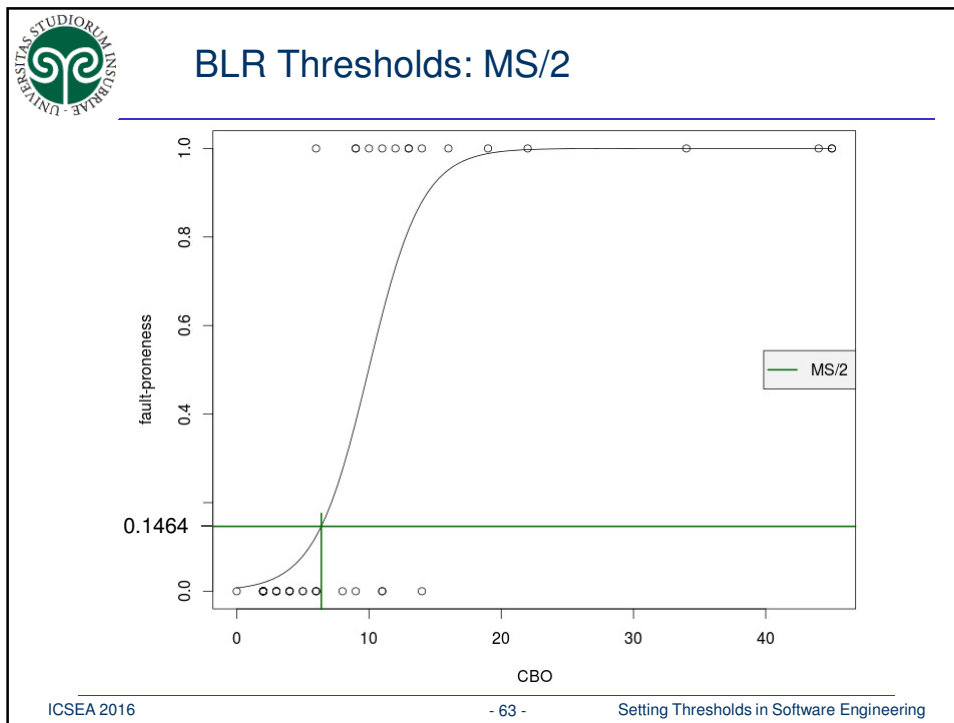
When $r=0.5$:

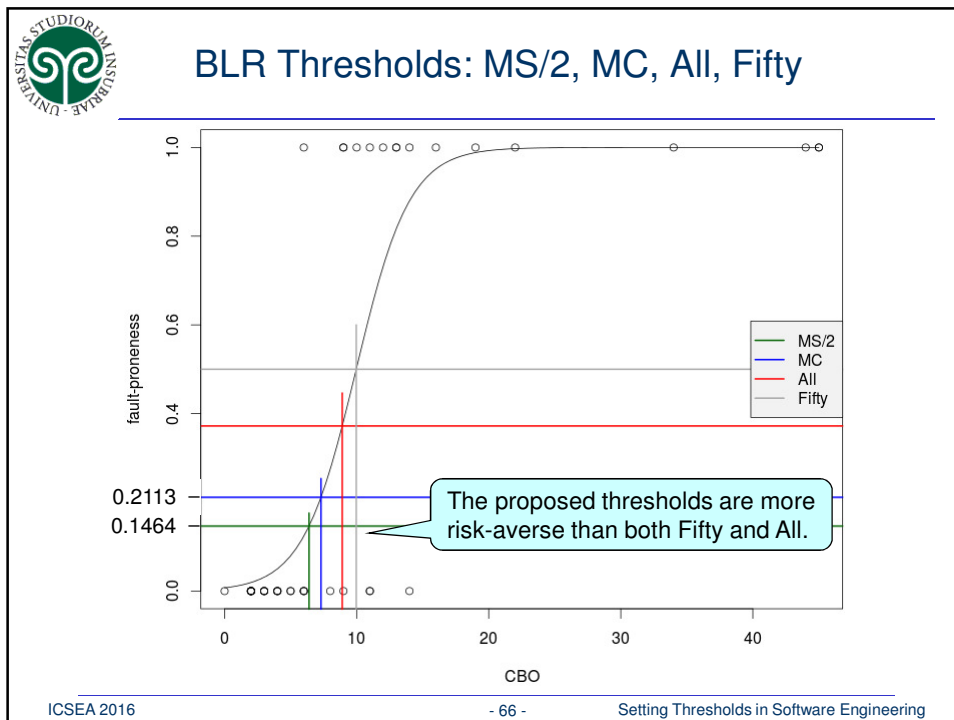
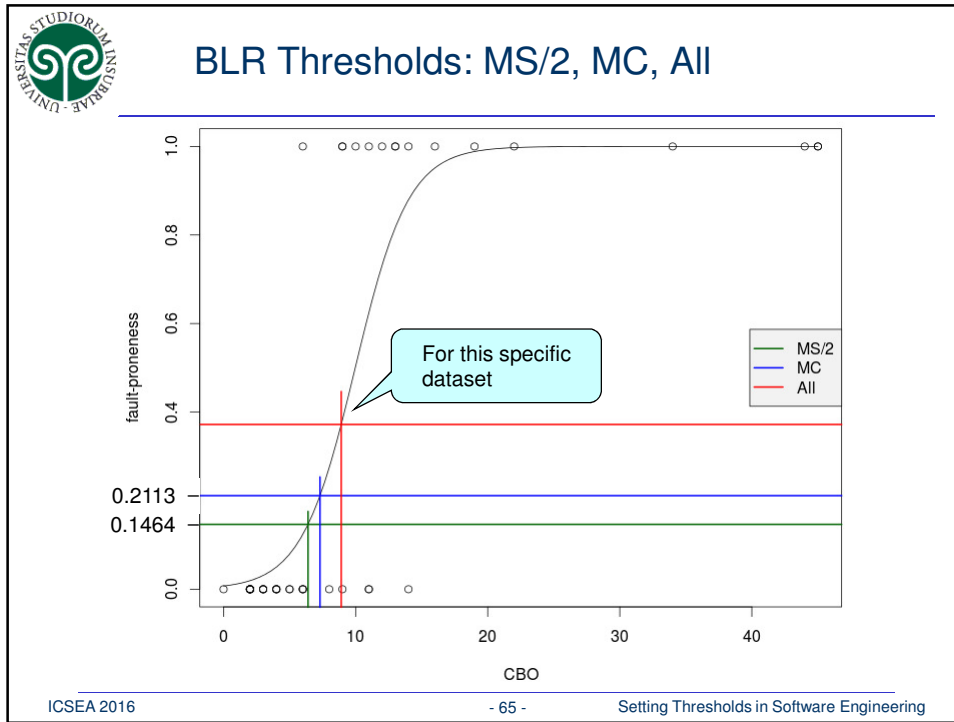
$$x_{MS/2} \approx -\frac{0.7656 + c_0}{c_1}$$


$$fp(x_{MS/2}) \approx 0.1464$$

The slope is always half the maximum when $fp=0.1464$

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What about PBR models?

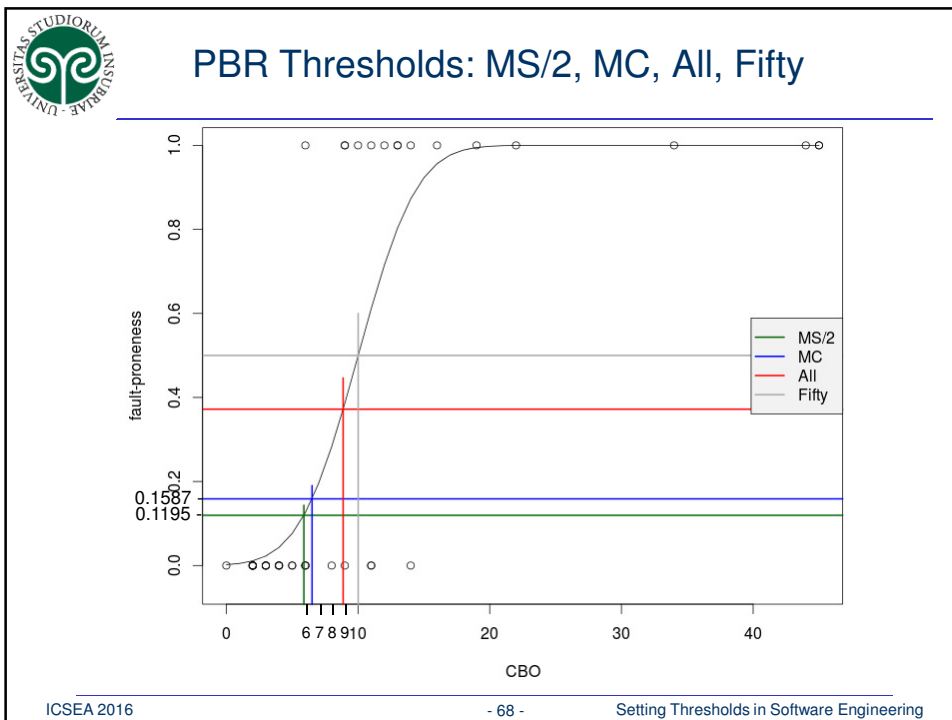
- Results of the mathematical analysis:
 - ▶ For any BLR model, maximum convexity occurs at the same values of fp.
 - ▶ For any BLR model, half maximum slope occurs at the same values of fp.
 - ▶ For any PBR model, maximum convexity occurs at the same values of fp.
 - ▶ For any PBR model, half maximum slope occurs at the same values of fp.


Fault-proneness values per type of model and type of threshold.

Model	MS/2	MC
PBR	0.1195	0.1587
BLR	0.1464	0.2113

- The values in the table above **apply to all** BLR and PBR models.

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Empirical study

- We used real-life datasets hosted on the PROMISE repository, with data on
 - ▶ module actual faultiness
 - ▶ several independent variables
- We carried out T-time K-fold cross-validation
 - ▶ 10-time 10-fold cross-validation for larger datasets
 - ▶ 5-time 5-fold cross-validation for smaller datasets
- For each fold, we built statistically significant univariate BLR and PBR models for all internal attribute measures
- We computed overall average Precision, Recall, F-measure

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Accuracy indicators

- Precision: proportion of estimated positives that are actually positive


$$Precision = \frac{TP}{EP}$$
- Recall: proportion of actual positives that are estimated positives

$$Recall = \frac{TP}{AP}$$

Recall indicates how risk-averse is the estimate.
Recall=1 means that all actual positives are estimated positive.
- F-measure: harmonic mean of Precision and Recall

$$FM = \frac{2}{\frac{1}{Precision} + \frac{1}{Recall}}$$

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Berek Dataset: Average F-measures with BLR

var	All	0.5	MC	MS/2
WMC	0.80	0.79	0.74	0.65
CBO	0.82	0.77	0.83	0.81
RFC	0.88	0.88	0.88	0.88
CA	0.81	0.77	0.78	0.75
CE	0.73	0.69	0.81	0.77
LOC	0.91	0.91	0.91	0.88
MOA	0.69	0.69	0.52	0.54
CAM	0.69	0.69	0.75	0.75
AMC	0.73	0.73	0.70	0.68
Max CC	0.71	0.69	0.65	0.64

In bold the result provide by the best threshold, for each model.

- There seems to be no best threshold: **no threshold maximizes FM for all models.**

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Berek Dataset: Average Recall with BLR

var	All	0.5	MC	MS/2
WMC	0.75	0.69	0.81	0.94
CBO	0.88	0.75	0.94	0.94
RFC	0.94	0.88	0.94	0.94
CA	0.81	0.75	0.88	0.94
CE	0.75	0.63	0.94	0.94
LOC	0.94	0.94	0.94	0.94
MOA	0.56	0.56	0.75	1.00
CAM	0.75	0.69	0.94	0.94
AMC	0.75	0.69	0.88	0.88
Max CC	0.63	0.56	0.75	0.94


- MS/2 maximizes Recall for all models.** It is the best threshold with respect to recall.
- MC provides similar performance (it is a bit less risk-averse)

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Results for all datasets, with BLR Best model for each dataset

Project	var.	n	AP/n	F-measure		recall	
				max	thresholds	max	thresholds
ckjm	LCOM	10	0.50	0.86	MS/2	1.00	MS/2
intercafe	CBO	27	0.15	0.86	0.5	0.75	All 0.5 MC MS/2
ivy-1.1	LCOM	111	0.57	0.80	MC MS/2	1.00	MC MS/2
lucene-2.2	NPM	247	0.58	0.79	MC MS/2	1.00	MC MS/2
lucene-2.4	RFC	340	0.60	0.75	MC MS/2	1.00	MC MS/2
nieruchomosci	MaxCC	27	0.37	0.89	MS/2	1.00	MS/2
pbeans1	LCOM	26	0.77	1.00	MC MS/2	1.00	MC MS/2
pdftranslator	LCOM	33	0.45	0.81	MC	1.00	MS/2
poi-1.5	LCOM	237	0.59	0.76	0.5	1.00	MC MS/2
poi-2.5	WMC	385	0.64	0.83	0.5	1.00	MC MS/2
poi-2.5	NPM	385	0.64	0.83	0.5	1.00	MC MS/2
poi-2.5	LCOM3	385	0.64	0.83	0.5	1.00	MC MS/2
poi-3.0	RFC	442	0.64	0.82	0.5	1.00	MC MS/2
poi-3.0	CE	442	0.64	0.82	tr	1.00	MC MS/2
sklebagd	WMC	20	0.60	0.92	MC	1.00	MC MS/2
szybkafucha	CBO	25	0.56	0.89	MC MS/2	0.80	MC MS/2
velocity-1.4	RFC	196	0.75	0.92	MC MS/2	1.00	MC MS/2
workflow	RFC	39	0.51	0.77	MC MS/2	1.00	MC MS/2
xerces-1.4	CBO	588	0.74	0.96	0.5	1.00	MC MS/2
xalan-2.5	NOC	803	0.48	0.70	MC MS/2	1.00	MC MS/2
zuzel	RFC	29	0.45	0.80	MC	0.92	MC MS/2
kalkulator	AMC	27	0.22	0.80	0.5	0.67	All 0.5 MC MS/2
wspomaganiepi	MOA	18	0.67	1.00	MC MS/2	1.00	MC MS/2

- MS/2 always maximizes Recall (and often also FM) 
- MC achieves similar results


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Results for PBR

- For PBR models we got very similar results.


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Summary of results

- MC and MS/2 have
 - ▶ almost always better Recall than the other thresholds
 - ▶ often better F-measure than the other thresholds
- The introduced thresholds are
 - ▶ suitable for identifying “early symptoms” of possible faultiness of a module
 - ▶ derived from properties of the fault-proneness model
 - ▶ computed automatically
 - ▶ quite accurate in terms of Recall and often F-measure too

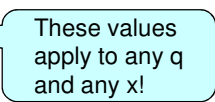
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Conclusions

- If you have a BLR or PBR model $q(x)$ that relates an interesting external quality q to some internal measure x
- You can use the following thresholds on q

Model	MS/2	MC
PBR	0.1195	0.1587
BLR	0.1464	0.2113




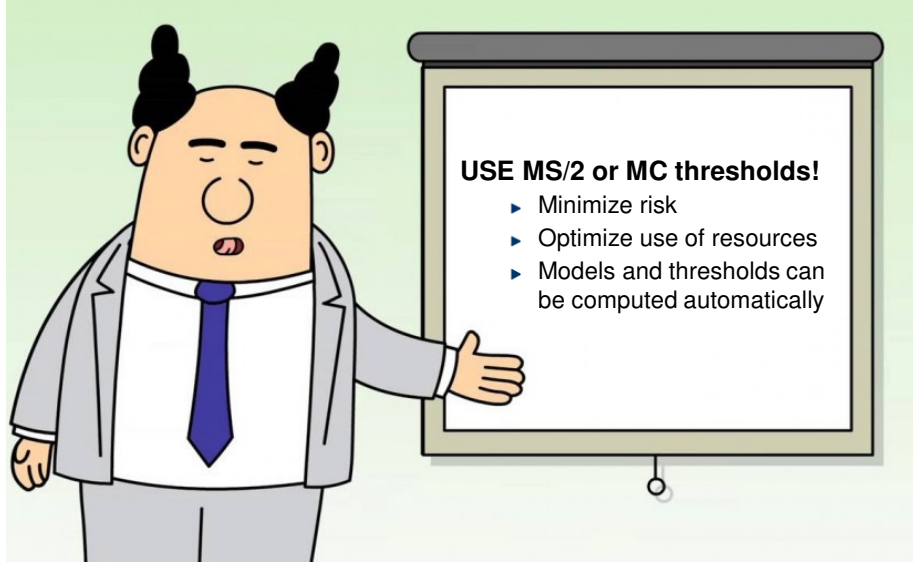
These values apply to any q and any x !

to get risk-averse thresholds on x .

- According to our experimental results, you maximize the number of actually positive modules that are estimated positives, while you still get relatively few negative modules that are estimated positives.
- This means that you get an excellent trade-off between
 - ▶ the effectiveness of the development and maintenance effort
 - ▶ the costs of quality improvement
 - ▶ the costs of using faulty software

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 **Conclusions**



USE MS/2 or MC thresholds!


- ▶ Minimize risk
- ▶ Optimize use of resources
- ▶ Models and thresholds can be computed automatically

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▶	Proposal 2: optimistic-pessimistic approach
	Proposal 3: fault-proneness H-index
	Final considerations

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The context

- In this case, we consider what happens at the end of the coding phase:
- You have a bunch of new modules and have to decide which of these modules deserve “special treatment” (e.g., code inspection) because they are likely faulty.

- Modules developed in the past --whose faultiness is known-- are the training set
- New modules --whose faultiness is unknown-- are the test set.


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Conventional Approach

1. A fault-proneness model is derived from the training set
2. The model is used to estimate the test set
 - To this end, a threshold on fp can be set
 - based on local considerations
 - as $\frac{AP_{trainingSet}}{n_{trainingSet}}$
- When actual faultiness data on the test set become available the accuracy of the estimates can be computed.

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The optimistic-pessimistic approach²

- The test set is used to build two models:
 - ▶ An optimistic one
 - ▶ A pessimistic one
- Where the models agree, you can be reasonably confident that the obtained classification is right.
- When the models disagree, you should better consider the faultiness of the module in question “uncertain”

²Luigi Lavazza and Sandro Morasca, “Identifying Thresholds for Software Faultiness via Optimistic and Pessimistic Estimations”, ESEM 2016

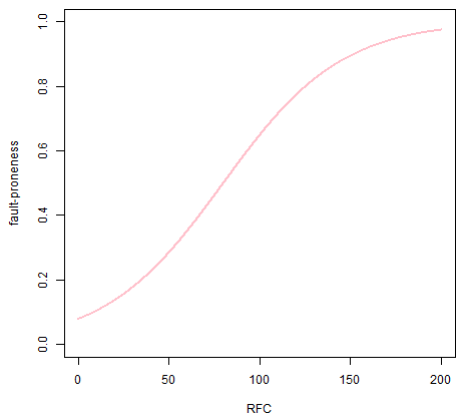
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Building the optimistic model


- All the modules in the test set are considered as not faulty
 - ▶ This is an optimistic assumption!
- You make the union of the training set and the test set
- You build a BLR model as usual

- The resulting model is optimistic, because of the initial optimistic assumption.



The graph shows a smooth, S-shaped curve representing the relationship between RFC (x-axis, 0 to 200) and fault-proneness (y-axis, 0.0 to 1.0). The curve starts at approximately (0, 0.1) and levels off towards (200, 1.0).

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Building the pessimistic model

- All the modules in the test set are considered as not faulty
 - ▶ This is a pessimistic assumption!
- You make the union of the training set and the test set
- You build a BLR model as usual

- The resulting model is pessimistic, because of the initial pessimistic assumption.

RFC	fault-proneness
0	0.15
50	0.45
100	0.75
150	0.90
200	1.00

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Optimistic Model Threshold and Optimistic Estimated Faultiness Model

- Select a threshold for the optimistic model and build an optimistic estimated faultiness model

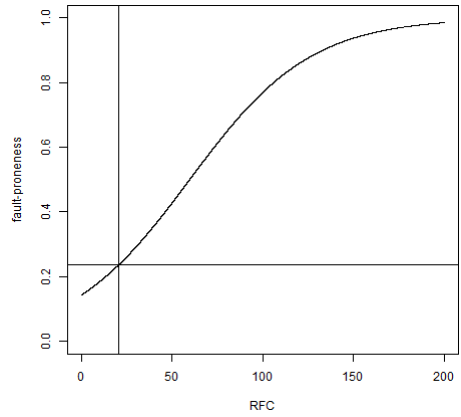
RFC	fault-proneness
0	0.00
50	0.25
100	0.65
150	0.85
200	1.00

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Pessimistic Model Threshold and Pessimistic Estimated Faultiness Model

- Select a threshold for the pessimistic model and build a pessimistic estimated faultiness model

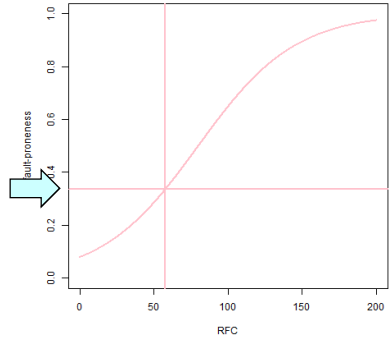


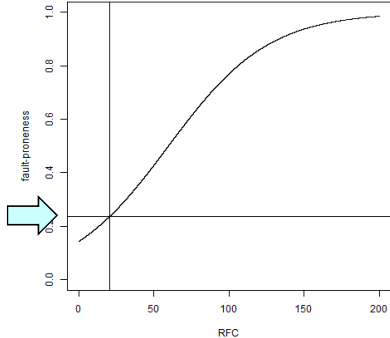
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Where to place fp thresholds?

- As usual, we have to decide where to place thresholds for fault-proneness.





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Possible fp thresholds

- Several thresholds are possible:
 - ▶ Pessimistic threshold: fraction of modules that are known to be positive

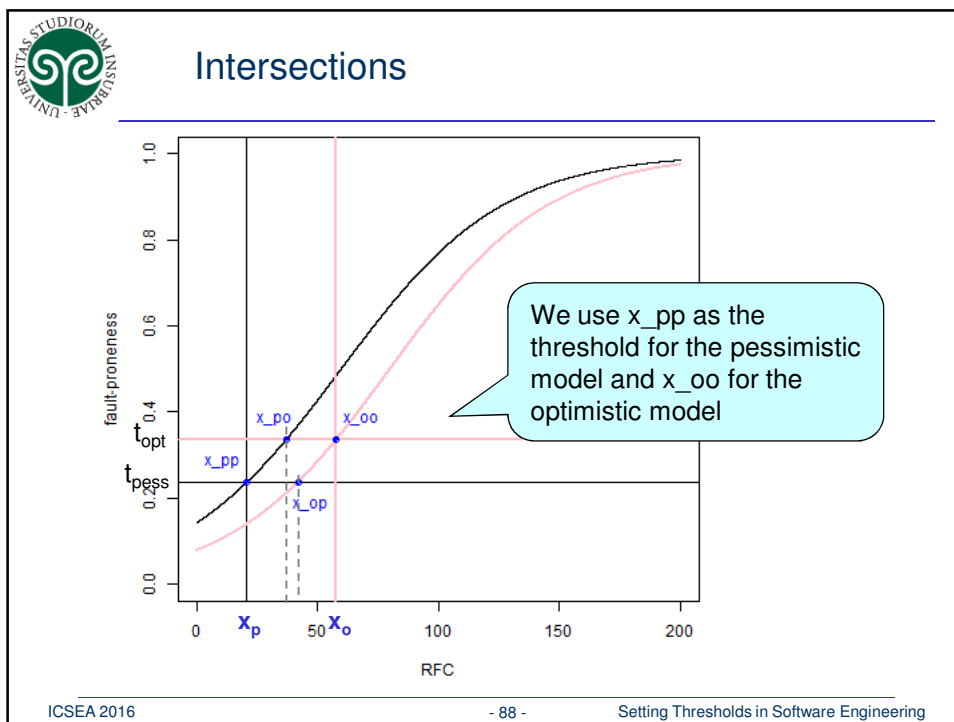
$$t_{pess} = \frac{AP_{trainingSet}}{n_{trainingSet} + n_{testSet}}$$
 - ▶ Optimistic threshold: fraction of modules that are known to be positive or are unknown

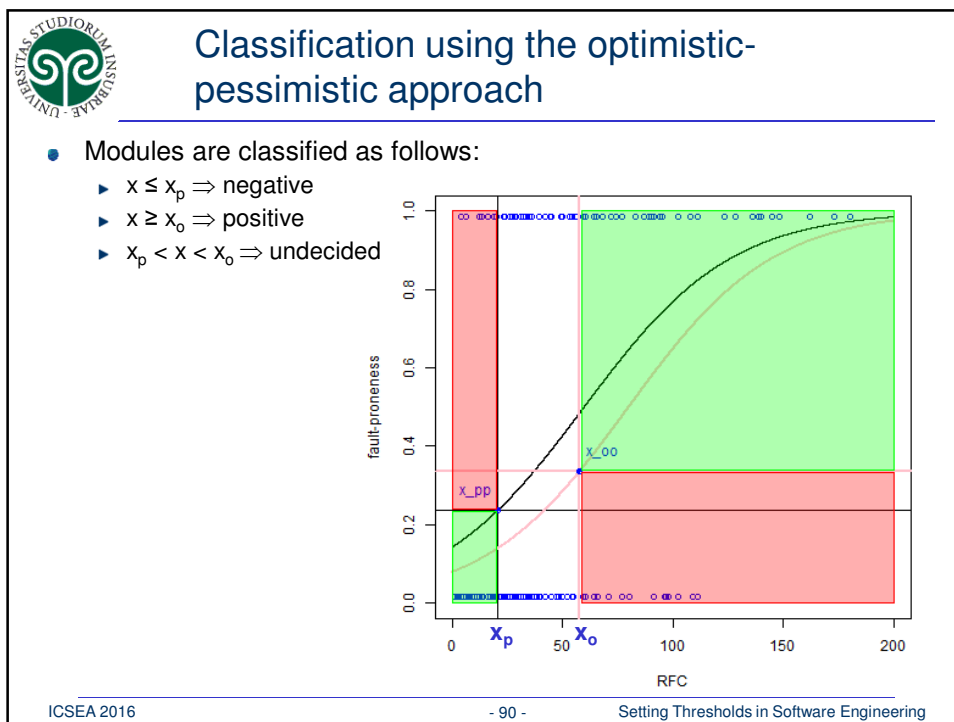
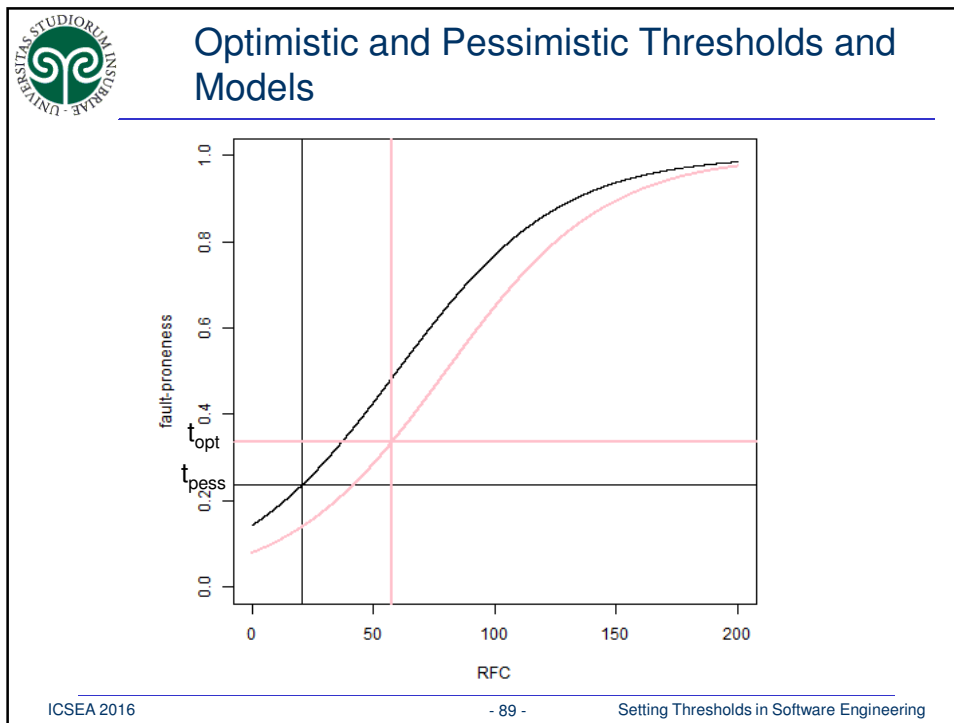
$$t_{opt} = \frac{AP_{trainingSet} + UK}{n_{trainingSet} + n_{testSet}}$$

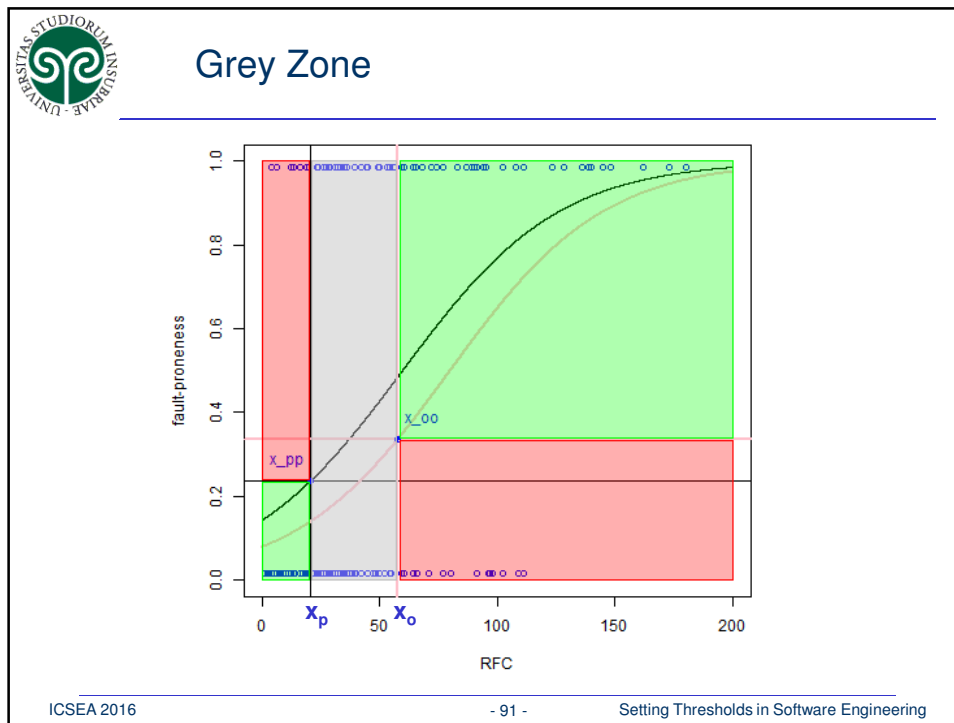
UK is the number of unknown, i.e., $n_{testSet}$
 - ▶ Neutral threshold:


$$t_{neut} = \frac{AP_{trainingSet}}{n_{trainingSet}}$$
- Note that $t_{opt} > t_{neut} > t_{pess}$

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 Other estimation approaches

- The reference approach
 - ▶ The test set is classified based on the model derived from the training set
- The pessimistic model approach alone
 - ▶ $x \leq x_{pp} \Rightarrow$ negative
 - ▶ $x > x_{pp} \Rightarrow$ positive
- The optimistic model approach alone
 - ▶ $x \leq x_{oo} \Rightarrow$ negative
 - ▶ $x > x_{oo} \Rightarrow$ positive


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Comparison

- We compared the classification obtained using the optimistic-pessimistic approach with the classifications obtained using other approaches.
- Note: when considering the optimistic-pessimistic approach, only classified modules were considered in the computation of the accuracy indicators.

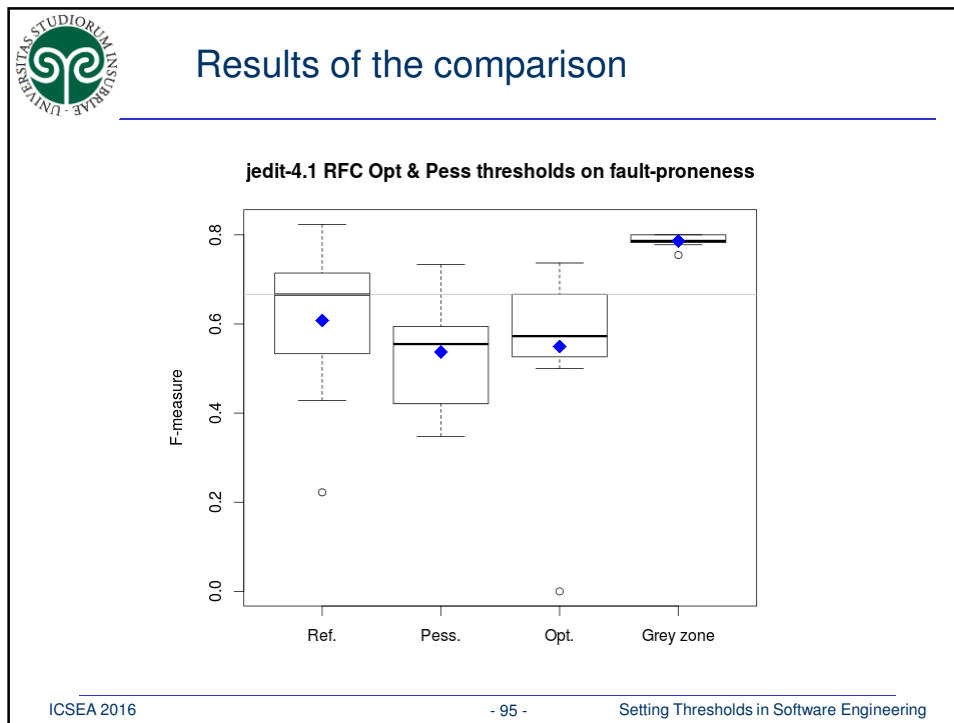
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Data sets

- We used 48 real-life datasets hosted on the PROMISE repository
- We carried out 10-fold cross-validation
- We almost always obtained the best results with
 - ▶ $x_p = x_{pp}$ and $x_o = x_{oo}$, or
 - ▶ $x_p = x_{po}$ and $x_o = x_{oo}$



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 Conclusion

- By means of the traditional approach you get quite variable results, because modules in the grey zone are classified as either faulty or not faulty anyway.
- With the optimistic-pessimistic approach the modules in the grey zone are not estimated, thus avoiding many classification errors.
- Note: if a module is in the grey zone of the CBO models, it could very well be out of the grey zone of the RFC model ...

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 <h2>Proposal³</h2>	
•	A new approach to building an estimated faultiness model based on the definition of the Fault-proneness H-Index, an extension to the H-index
•	Basic idea <ul style="list-style-type: none"> ▶ the H-Index identifies the most important papers of a researcher ▶ the Fault-proneness H-Index identifies the most fault-prone modules in a set of modules
•	Advantage <ul style="list-style-type: none"> ▶ we do not need to set a threshold ourselves, but the threshold is derived from the data

³Sandro Morasca, "Classifying Faulty Modules with an Extension of the H-index," ISSRE 2015


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H-index computation

- Order absolute frequencies $af(z)$ in decreasing order
- Set $z = 0$ as the initial value of the H-Index
- Increase the value of z by 1 as long as $af(z) \geq z$
- The value of the H-index is the last value z such that $af(z) \geq z$
- The value of h can be found at the intersection of two functions
 - ▶ $af(z)$, which is decreasing
 - ▶ z , which is linearly increasing


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My H-index

Rank	Title	Citations	Authors	Journal/boo
1	SPADE: An environment for software process analysis, design, and enactment	196	S Bandinelli, A Fuggetta, C Ghezzi, L Lavazza	Software prc
2	Modeling and improving an industrial software process	156	S Bandinelli, A Fuggetta, L Lavazza, M Loi, GP Pici	IEEE Transac
3	A conceptual basis for feature engineering	146	C Reid Turner, A Fuggetta, L Lavazza, AL Wolf	The Journal
4	Deriving executable process descriptions from UML	122	E Di Nitto, L Lavazza, M Schiavoni, E Tracanella,	Proceedings
5	Combining UML and formal notations for modelling real-time systems	89	L Lavazza, G Quaroni, M Venturelli	ACM SIGSOF
6	Applying QQM in an industrial software factory	66	A Fuggetta, L Lavazza, S Morasca, S Cinti, G ...	ACM Transa
7	The architecture of SPADE-1 process-centered SEE	61	S Bandinelli, M Braga, A Fuggetta, L Lavazza	Lecture Note
8	Translation and optimization of logic queries: the algebraic approach	56	S Ceri, G Gottlob, L Lavazza	Proceedings
9	The GOODSTEP Project: General Object-Oriented Database for Software Engineering	48	The GOODSTEP Team	APSEC'94
10	Algres: an advanced database system for complex applications	50	S Ceri, S Crespi-Reghizzi, R Zicari, G Lamperti, LA	IEEE Softwar
11	Providing automated support for the GQM measurement process	52	L Lavazza	IEEE Softwar
12	OpenBQR: a framework for the assessment of OSS	50	Davide Taibi, Luigi Lavazza and Sandro Morasca	OSS 2007
13	Feature engineering	44	CR Turner, AL Wolf, A Fuggetta, L Lavazza	Proceedings
14	An experience in process assessment	40	F Cattaneo, A Fuggetta, L Lavazza	Proceedings
15	Combining Problem Frames and UML in the Description of Software Requirements	30	L Lavazza, V. Del Bianco	FASE 2006
16	SystemC/C-based model-driven design for embedded systems	29	Riccobene, Scandurra, Bocchio, Rosti, Lavazza, M	TECS
17	Model-based functional size measurement	33	Lavazza, Del Bianco, Garavaglia	ESEM 2008
18	Enhancing Requirements and Change Management through Process Modelling	31	Lavazza, Valetto	ICRE 2000
19	A UML-based approach for representing problem frames	25	L Lavazza, V. Del Bianco	IEE Seminar
20	A case study in COSMIC functional size measurement: The rice cooker revisited	27	L Lavazza, V. Del Bianco	Software Prc
21	Automated support for process-aware definition and execution of measurement pla	25	Lavazza, Barresi	ICSE2005
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23	Requirements-based estimation of change costs	22	L Lavazza, G Valetto	
24	An investigation of the users' perception of OSS quality	21	Del Bianco, Vieri, Luigi Lavazza, Sandro Morasca,	OSS 2010
25	Model checking UML specifications of real time software	24	Del Bianco, V. Lavazza, L. Mauri, M.	ICECCS 2002
26	A Survey on Open Source Software Trustworthiness	21	Del Bianco, Vieri, Luigi Lavazza, Sandro Morasca,	IEEE SW
27	Managing software artifacts on the Web with Labyrinth	21	Cattaneo, Fabiano, Elisabetta Di Nitto, Alfonso	ICSEA 2000
28	Quality of Open Source Software: The QualiPSo Trustworthiness Model	19	Del Bianco, V. and Lavazza, L. and Morasca, S.	ar.OSS 2009

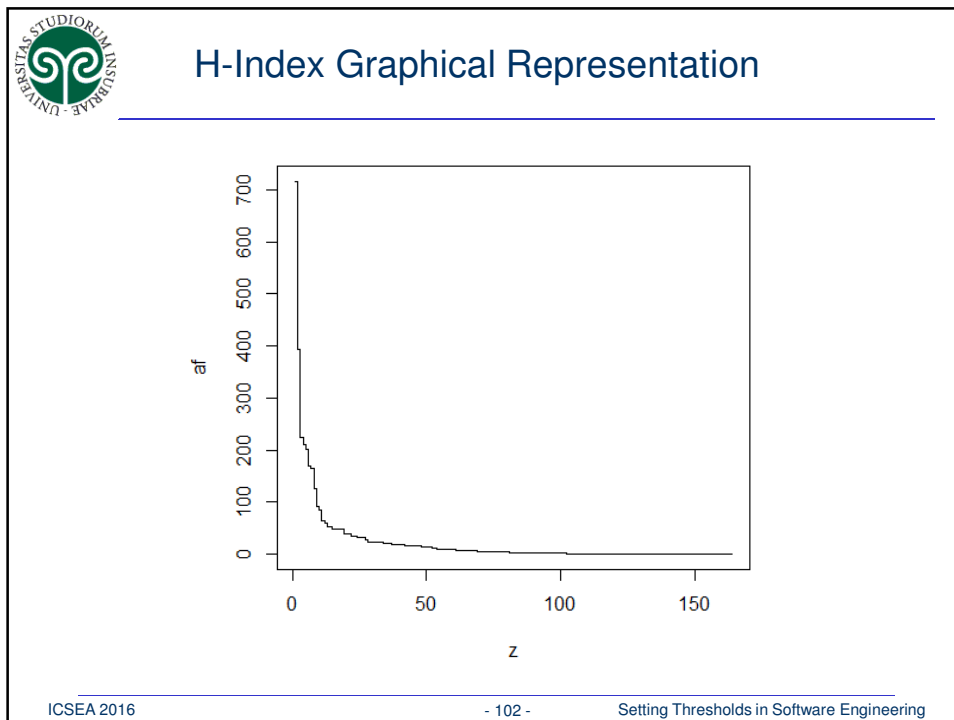
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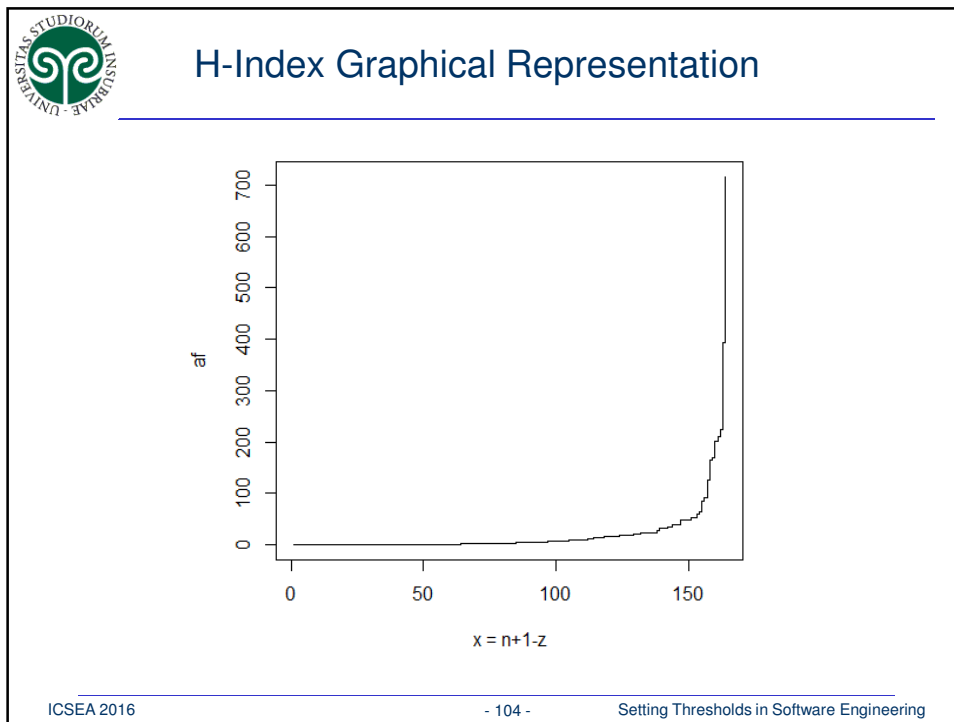
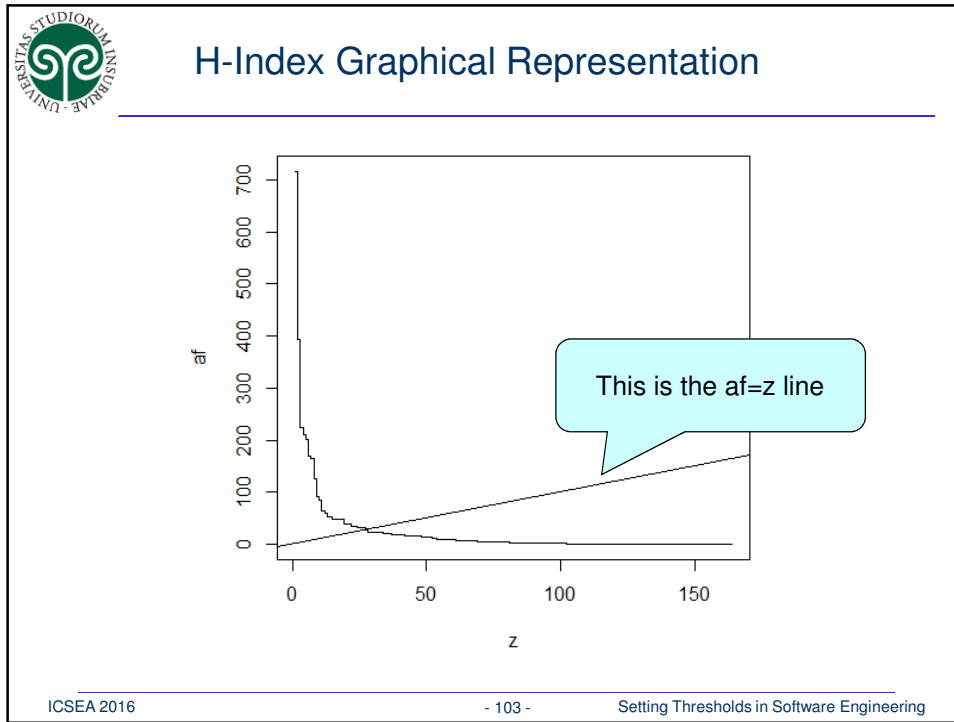


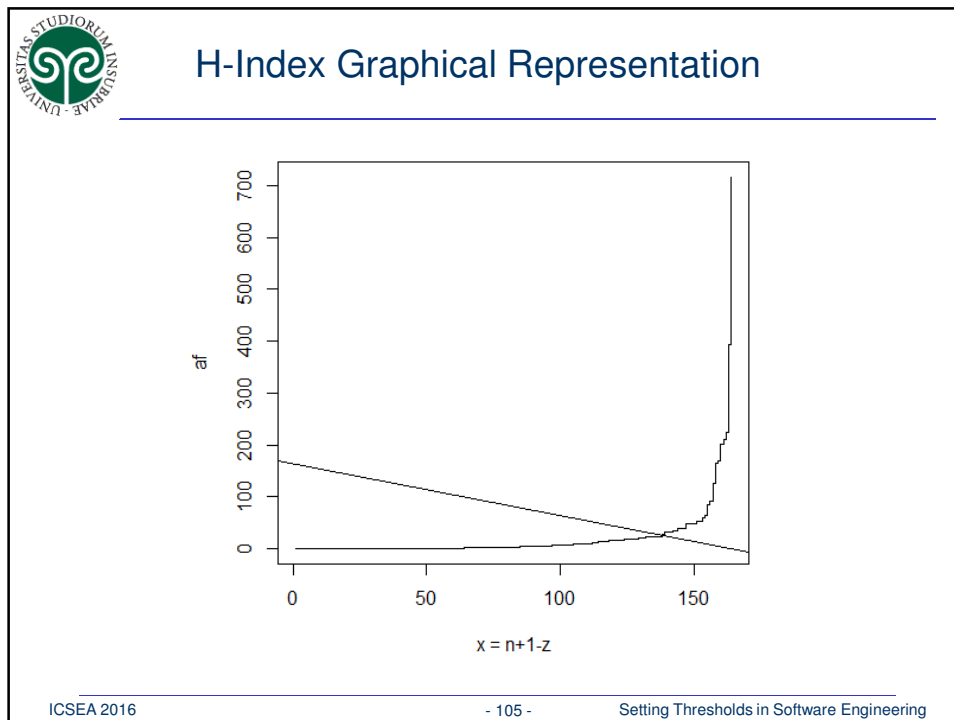
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5	Combining UML and formal notations for modelling real-time systems	89	L Lavazza, G Quaroni, M Venturelli	ACM SIGSOFT Software Engi
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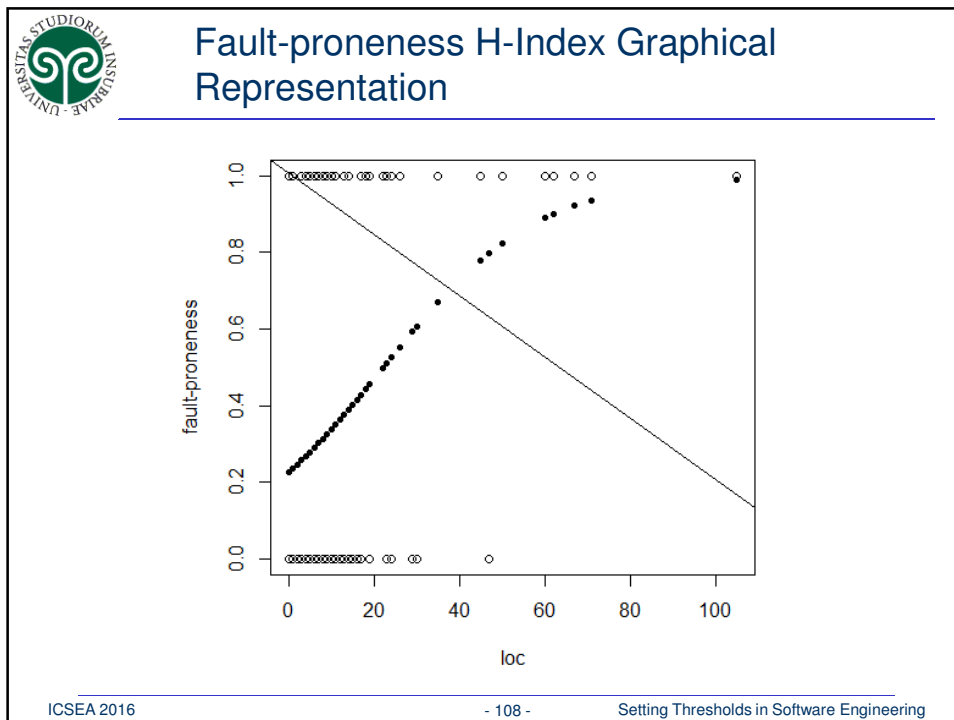
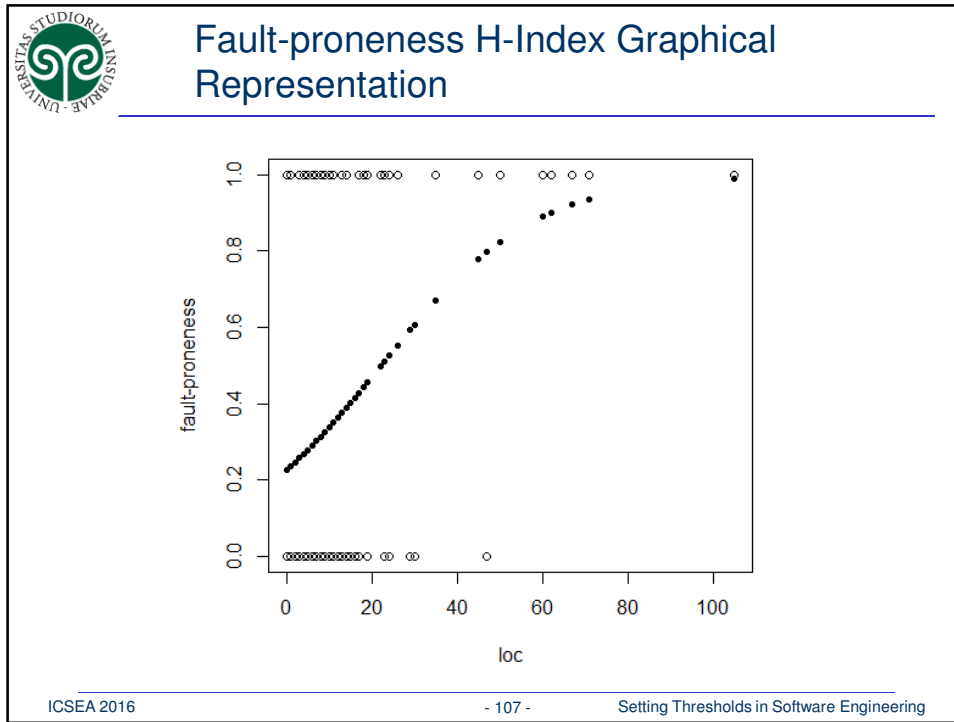





 Fault-proneness H-Index Computation

- Order the modules in decreasing order of estimated fault-proneness FP
- Set $z = 0$ as the initial value of the FPH-Index
- Increase the value of z by $1=n$ as long as $FP(x_m) \geq z/n$
- The value of fph is the last value of $FP(x_m)$ for which $FP(x_m) \geq z/n$ holds
- The value of fph can be found at the intersection of two functions
 - ▶ $FP(x_m)$, which is decreasing with z
 - ▶ z/n , which is linearly increasing

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Results

- The H-index-based estimation technique
 - ▶ has generally higher values of Recall
 - ▶ has generally lower values of Precision
 - ▶ has generally higher values of F-measure when the weight of Recall is comparatively high


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Estimates based uniquely on internal measures

- Do we get good results (i.e., accurate estimates) with this strategy?
- Not really⁴.
- Let's see some experimental results.

⁴ L. Lavazza, S. Morasca, "An Empirical Evaluation of Distribution-based Thresholds for Internal Software Measure", *PROMISE 2016*.

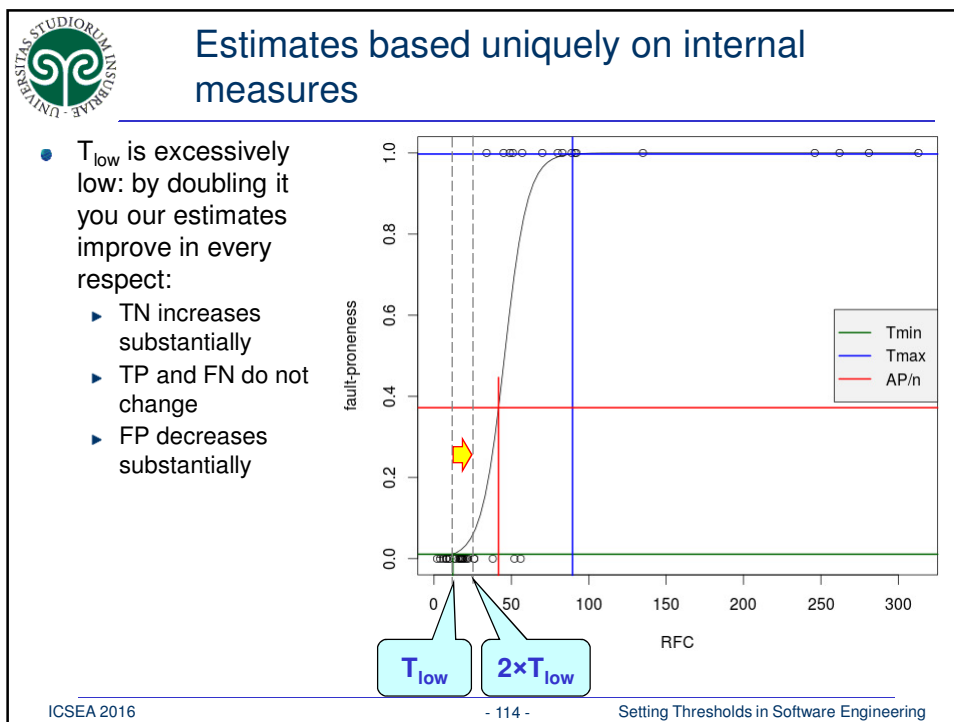
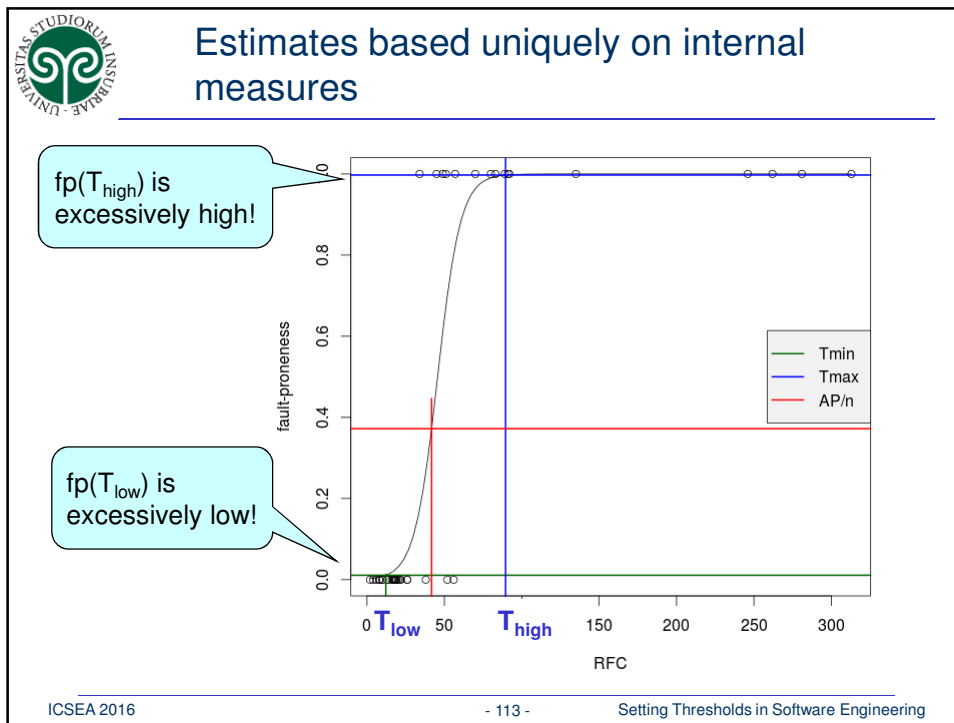
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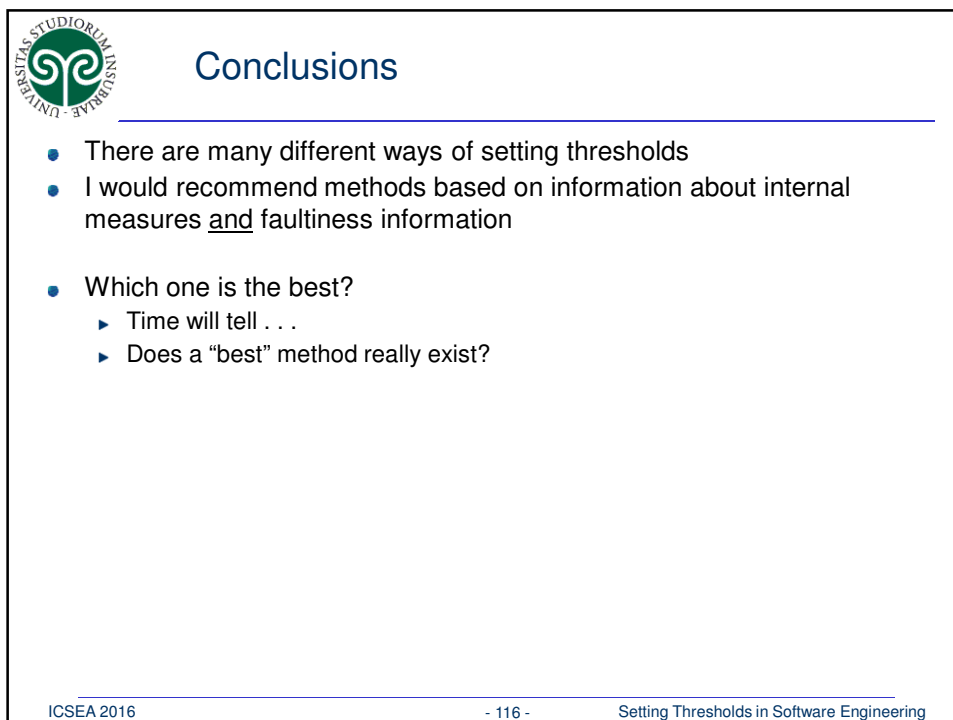
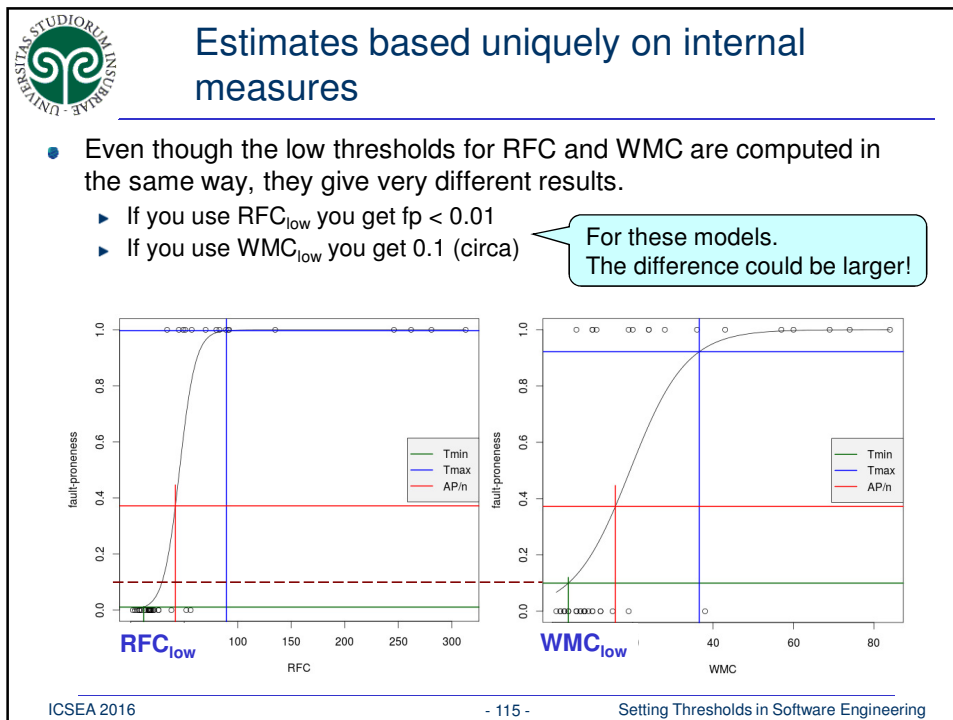



Estimates based uniquely on internal measures

- Let us consider the proposal by Erni & Lewerentz (or by Lanza and Marinescu)
- $T_{low} = \mu - \sigma$
- $T_{high} = \mu + \sigma$
- Where μ is the mean and σ is the standard deviation
- The threshold do not depend on faultiness data, but just in internal measures.
- What happens when we take into consideration faultiness data?
- Let's see how the thresholds behave in fault-proneness models.

ICSEA 2016 - 112 - Setting Thresholds in Software Engineering





 **Future work**

- A lot . . .

ICSEA 2016 - 117 - Setting Thresholds in Software Engineering



A cartoon illustration of a man with a large nose and a yellow shirt, holding a white mug. He is standing next to a whiteboard that has the word "QUESTIONS?" written on it with a curved line pointing to the text.

ICSEA 2016 - 118 - Setting Thresholds in Software Engineering